## POC-M

# **Control module with integrated pressure sensor e.g. for central extraction systems**

## **Operating Instructions**



Keep for reference!

Software version: from version 11.16



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## 1 General notes

#### 1.1 Structure of the operating instructions

Before installation and start-up, read this manual carefully to ensure correct use! We emphasize that these operating instructions apply to specific units only, and are in no way valid for the complete system!

Use these operating instructions to work safely with and on the device. They contain safety instructions that must be complied with as well as information that is required for failure-free operation of the device.

Keep these operating instructions together with the device. It must be ensured that all persons that are to work on the device can refer to the operating instructions at any time.

Keep the operating instructions for continued use. They must be passed-on to all successive owners, users and final customers.

#### 1.2 Target group

The operating instructions address persons entrusted with planning, installation, commissioning and maintenance and servicing and who have the corresponding qualifications and skills for their job.

#### 1.3 Exclusion of liability

Concurrence between the contents of these operating instructions and the described hardware and software in the device has been examined. It is still possible that non-compliances exist; no guarantee is assumed for complete conformity. To allow for future developments, construction methods and technical data given are subject to alteration. We do not accept any liability for possible errors or omissions in the information contained in data, illustrations or drawings provided. We accept no liability for damage caused by misuse, incorrect use, improper use or as a consequence of unauthorized repairs or modifications.

#### 1.4 Copyright

These operating instructions contain copyright protected information. The operating instructions may be neither completely nor partially photocopied, reproduced, translated or put on data medium without previous explicit consent. Infringements are liable for damages. All rights reserved, including those that arise through patent issue or registration on a utility model.

## 2 Safety instructions

This chapter contains instructions to prevent personal injury and property damage. These instructions do not lay claim to completeness. In case of questions and problems, please consult our company technicians.

#### 2.1 Intended use

The equipment is to be used solely for the purposes specified and confirmed in the order. Any other use above and beyond this is considered not for the intended purpose unless agreed otherwise by contract. The manufacturer will not be liable for any damage resulting from this. The individual or company using it bears the sole risk.

Reading these operating instructions and complying with all contained instructions - especially the safety notifications contained therein - are considered part of intended use. To consider is also the manual of attached components. Not the manufacturer, rather the operator of the device is liable for any personal harm or material damage arising from non-intended use!



#### 2.2 Explanations of symbols

Safety instructions are highlighted with warning triangles and are depicted according to the degree of hazard as follows.

	Attention! General hazardous area. Death or severe injury or significant property damage can occur if the corresponding precautions are not taken!
	Danger due to electric current Danger by dangerous, electric voltage! Death or severe injury can occur if the corresponding precautions are not taken!
1	Information Important additional information and advice for user.

#### 2.3 Product safety

The device conforms to the state of the art at the time of delivery and is fundamentally considered to be reliable. The device and its accessories must only be used in a flawless condition and installed and operated in compliance with the assembly instructions and/or operating instructions. Operating outside the device's technical specifications (P name plate and attachment / technical data) can lead to a defect in the device and additional damage!

In the case of a malfunction or a failure of the equipment check all functions with alarms in order to prevent injury to persons or property. Note possibility of back-up operation. If used in intensive animal environments, any malfunctions in the air supply must be detected as soon as possible to prevent the development of a life-threatening situation for the animals. The design and installation of the system must comply with local regulations and directives. In Germany these include DIN VDE 0100, the animal protection and the keeping of working animals ordinance and the pig-keeping ordinance etc. Also note the instructions of AEL, DLG, VdS.

#### 2.4 Requirements placed on the personnel / due diligence

Persons entrusted with the planning, installation, commissioning and maintenance and servicing in connection with the frequency inverter must have the corresponding qualifications and skills for these jobs.

In addition, they must be knowledgeable about the safety regulations, EU directives, rules for the prevention of accidents and the corresponding national as well as regional and in-house regulations. Personnel to be trained or instructed and apprentices are only permitted to work on the device under the supervision of an experienced person. This also applies to personnel undergoing general training. Comply with the legal minimum age.

#### 2.5 Start-up and during operation



#### Attention!

- During commissioning, unexpected and hazardous conditions can arise in the entire installation due to defective adjustments, defective components or incorrect electrical connections. Remove all persons and objects from the hazardous area.
- During operation, the device must be closed or installed in a control cabinet. Fuses may only be replaced by new ones and must not be repaired or bypassed. The data for the maximum line fuse are to be considered absolutely (@ Technical data). Use only fuses specified in schematic diagrams.
- Any faults detected in the electric system/modules/operating equipment must be corrected immediately. If these faults are not corrected, the device/system is potentially very dangerous. The device/system must therefore not be operated when it is faulty.
- Pay attention to smooth, low vibration running of the motor/fan, the appropriate instructions in the drive documentation must be observed!



#### 2.6 Work on the device



#### Information

Mounting, electrical connection, and start-up operation may only be carried out by an electrical specialist in accordance with electrotechnical regulations (e.g. EN 50110 or EN 60204)!



#### Danger due to electric current

It is generally forbidden to carry out work on electrical live parts. Protection class of the device when open is IP00! It is possible to touch hazardous voltages directly. The safe isolation from the supply must be checked using a **two-pole** voltage detector.



#### Attention!

Automatically restart after a power failure or mains disconnection!

#### 2.7 Modifications / interventions in the device



#### Attention!

For reasons of safety, no unauthorized interventions or modifications may be made on the device. All planned modifications must be authorized by the manufacturer in writing.

Only use the manufacturer's original spare parts / wearing parts / accessories. These parts are specially designed for this device. If parts from other sources are used, there is no guarantee that they are designed and produced for the proper loads and with the required level of safety. Parts and special equipment not supplied by the manufacturer are not approved for use.

#### 2.8 Operator's obligation of diligence

- The contractor or owner must also ensure that the electric systems and equipment are operated and maintained in accordance with electro-technical regulations.
- The owner is obliged to ensure that the device is operated in perfect working order only.
- The device may only be used as intended (@ "area of application").
- You must periodically examine the safety equipment for their properly functioning condition.
- The assembly instructions and/or operating instructions are always readily available at the location where the device is being used, are complete and are in legible condition.
- These persons are regularly instructed in all applicable questions regarding occupational safety and environmental protection and are knowledgeable regarding the assembly instructions and/or operating instructions and, especially, are familiar with the safety instructions contained therein.
- All safety and warning notices attached to the device are never removed and remain legible.

#### 2.9 Employment of external personnel

Maintenance and service work are frequently carried out by external employees who often do not recognize the specific situations and the thus resulting dangers. These persons must be comprehensively informed about the hazards in their area of activity.

You must monitor their working methods in order to intervene in good time if necessary.



## 3 Product overview

#### 3.1 Operational area

Control module with integrated pressure sensor e.g. for central extraction systems. In connection with an external temperature sensor outside temperature compensation is possible.

The purpose of the device is to reach and maintain the target values set. To accomplish this, the measured actual value (sensor value) is compared with the adjusted target value, and the controlled value (modulation) is deduced from this.

Controlled output (0 - 10 V) e.g. for activating a speed controller for fans or an EC-fan directly.

#### 3.2 Maintenance

The device must be checked for soiling and, if necessary, cleaned in periodic intervals.

#### 3.3 Transport

- The device is packed ex factory to suit the transport method previously agreed.
- Always use the original packaging materials when transporting the device.
- · Avoid shocks and impacts to the device during the transport.
- During manual handling the human lifting and carrying restrictions must be observed and adhered to.

#### 3.4 Storage

- The device must be stored in its original packaging in a dry and weather-proof room.
- Avoid exposure to extreme heat and cold.
- Avoid over-long storage periods (we recommend a maximum of one year).

#### 3.5 Disposal / recycling



Disposal must be carried out professionally and in an environmentally friendly way in accordance with the respective national legal stipulations.

 $\triangleright$  Separate the materials by type and in an environmentally friendly way.

 $\triangleright$  If necessary, commission a specialist company with the waste disposal.

## 4 Mounting

#### 4.1 General notes



#### Attention!

The following points must be complied with during the mechanical installation to avoid causing a defect in the device due to assembly errors or environmental influences:

- Before installation remove the device from the packing and check for any possible shipping damage!
- Assemble the device on a clean and stable base. Do not distort during assembly! Use the appropriate mounting devices for proper installation of the unit!
- Do not mount equipment on vibrating base!
- When mounted onto lightweight walls, there must be no impermissibly high vibrations or shock loads. Any banging shut of doors that are integrated into these lightweight walls, can result in extremely high shock loads. Therefore, we advise you to decouple the devices from the wall.
- Do not allow drilling chips, screws and other foreign bodies to reach the device interior!
- The device should be installed in a location where it will not be disturbed, but at the same time can be easily accessed!
- Depending on the housing model use supplied stoppers for cable inlets, cut off necessary cable inlets respectively to the cable diameter. Or alternative use cable inlet for cable glands. Any cable ducts openings not used must be sealed!
- Care must be taken to avoid direct radiation from the sun!
- The device is designed for vertical installation (cable inlet down). A horizontal or reclined installation is only permissible after technical release of the manufacturer!
- Be sure to observe proper heat dissipation (@Technical data, heat dissipation).



#### 4.2 Connection pressure measuring tube

Depending on the tube diamater cut the cable entries and bring in measuring tubes into the device. Connection of the tubes directly to the internal pressure sensor.

The excess pressure tube must be connected to the white side here "P1" (+) and the negative pressure tube connected to the black side "P2" (-) (connection piece  $\emptyset$  : 6.2 mm).



#### 4.3 Outdoor installation

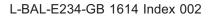
Outdoor installation is possible up to -20 °C when the controller supply is not switched off. Installation must be protected from the effects of weather as much as possible, including protection from direct sunlight!

#### 4.4 Installation location for agriculture

When using for animal keeping, do not install the device directly in the stable but in a separate room with a lower pollutant load. This helps to avoid damages caused by pollutant gases (e.g. ammonia fumes, hydrogen sulphide fumes).

#### 4.5 Temperature influences during commissioning

Avoid condensation in the controller and functional faults attributable to condensation by storing the controller at room temperature!





## 5 Electrical installation

#### 5.1 Safety precautions



#### Danger due to electric current

- Work on electric components may only be carried out by trained electricians or by persons instructed in electricity under the supervision of an electrician in accordance with electrical engineering regulations.
- The 5 electrical safety rules must be observed!
- It is forbidden to carry out work on electrically live parts.
- Other measures may be necessary to achieve safe electrical isolation.
- A second person must always be present when working on energized parts or lines who disconnects in case of emergency.
- Inspect electrical equipment periodically: retighten loose connections immediately replace damaged lines and cables.
- Always keep switch cabinets and all electrical supply facilities locked. Access is only allowed for authorized persons using a key or special tool.
- Operating the device with the housing cover removed is prohibited because energized, exposed parts are present inside the device. Disregarding this regulation can lead to severe personal injury.
- The required protective earth connection is established using screws between the housing parts in metal terminal space covers and housing casings. Commissioning is only permissible after these screws have been properly attached!
- The device owner is responsible for the EMC of the entire plant according to the locally applicable standards.
- Metal screwed-connections are not permitted in plastic housing parts because there is no potential equalization.
- Never clean electrical equipment with water or similar liquids.



#### Information

The respective connections are represented in the enclosure of this manual (@ Connection diagram)!

#### 5.2 EMC-compatible installation of control lines

Pay attention to sufficient distance from powerlines and motor wires to prevent interferences. The control cable may not be longer than 30 m. Screened control cables must be used when the cable length is longer than 20 m. When using a shielded cable connect the shielding to one side only, i.e. only to the control unit with the protective ground (keep cable short and with as little inductance as possible!).

#### 5.3 Mains connection

Power from the mains is connected to terminals: PE, L1 and N. Here, it must be strictly observed that the mains voltage lies within the allowable tolerance specifications ( Technical data and nameplate affixed to the side).



#### Danger due to electric current

The mains voltage must comply with the DIN EN 50160 quality characteristics and the defined standard voltages in IEC 60038!

#### 5.4 Signal input or sensor connection (E2)

- In the operating mode 4.01, the analogue input "E2" has no function ( basic setting 4.01).
- In the operating mode **4.02** (factory setting), the analogue input"E2" is pre-programmed for connecting the outdoor temperature sensor (PTC / KTY81-210 of the "TF.." series).
  - When connecting **passiv** temperature sensorsTF.. (KTY81-210) or PT1000 at terminals "E2" and "T" must be paid attention to no polarity.
     For a high interference immunity a capacitor must be connected directly to the sensor (1 nF)
    - For a high interference immunity a capacitor must be connected directly to the sensor (1 nF parallel). With temperature sensors type TF.. (KTY81-210) a capacitor is integrated.
  - When connecting aktive sensors at the terminals "E2" and "GND" attention must be paid to correct polarity, a 24 V DC power supply is integrated.
  - For sensors in two-wire-technology (4 20 mA signal), the connection is made on the "E2" and "24 V" ("GND" terminal is omitted).





Danger due to electric current

Never apply line voltage to analog inputs!



#### Information

Analog input "E1" is internally occupied by the built in pressure sensor.

#### 5.5 Control outputs 0 - 10 V (A1, A2)

The analogue outputs can be used to activate a speed controller with 0 - 10 V input for example. Fans with integrated controller and 0 - 10 V input can be activated directly.

- Analog output 1 (terminals A1 GND)
  - Controlled 0 10 V output for control circuit 1 (factory setting function [2A]).
- Analog output 2 (terminals A2 GND)
  - For operation with one control circuit: constant voltage +10 V e.g. for supply of an external potentiometer (function factory setting 1 A).
  - For operation with a second control circuit: controlled 0 10 V output for control circuit 2 (function initial setting 8 A).

Other functions can be assigned if necessary (@ Operating Instructions / IO Setup).



Danger due to electric current

It is not permissible to connect outputs of several devices to each other!

#### 5.6 Voltage supply for external devices (+24V, GND)

A voltage supply is integrated for external devices e.g. a sensor (max. current load restarted technical data). In case of overload or short circuit (24 V – GND), the external power supply is shut down (multi-fuse). The device performs a "Reset" and continues operation.

- It is not permissible to connect voltage outputs in the device to each other!
- It is not permissible to connect voltage outputs in the device to each other!

#### 5.7 Digital inputs (D1, D2)

Various functions can be allocated to the digital inputs "D1" and "D2" (P IO Setup: Functions summary of the digital inputs). Activation via floating contacts (a low voltage of ca. 24 V DC is connected).

Factory setting for digital input "D1": Switch over setpoint 1 / setpoint 2 (function = 5D) "Setpoint 1" with open contact / "setpoint 2" with closed contact. For operation with second control circuit: switch over "1.Setpoint 1" / "1.Setpoint 2"

Info	
248.3 Pa E1 Actual	Operation with "Setpoint2" is signalized by the moon symbol for reduced operation.

No function is programmed in factory for the digital input "D2" (function = OFF)



**Danger due to electric current** Never apply line voltage to the digital input! Observe input resistance and voltage range (@ Technical data).

#### 5.8 Relay outputs (K1, K2)

Various functions can be allocated to the relay outputs "K1" and "K2" (@ IO Setup: function and inverting relais outputs). Max. contact rating @ technical data and connection diagram.

#### Relays K1

- Connection of the floating contacts of relay "K1" to the terminals 11, 14, 12.
- "K1 Function" factory setting: <u>1K</u> = **Operating indication**. I.e. energized for operation without fault, for enable "OFF" de-energized.

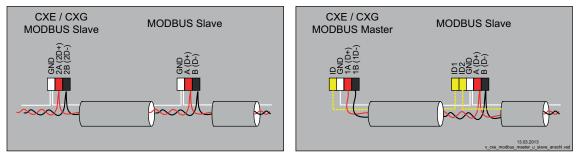
#### **Relays K2**

- Connection of the floating contacts of relay "K2" to the terminals 21, 24, 22.
- "K2 Function" factory setting: 2K = Fault indication. I.e. energized for operation without fault and for enable "OFF".

#### 5.9 RS-485 interfaces for MODBUS RTU

The device has two RS-485 interfaces for networking via MODBUS RTU:

- 1. Interface "1A (1D+)", "1B (1D-)" for MODBUS Master applications
- Pre-programmed function is output from control circuit 1: 1. Control signal (2A)
   e.g. for activating speed controllers for fans or fans with integrated controller and MODBUS interface (@ member MODBUS Master).
   The programmable functions correspond to the functions for the analogue outputs described in
- the IO Setup.
  Automatic addressing of members via a patented procedure.
  It is no longer necessary to address each individual member manually in the network. The "ID" connection is also assigned (for more information P the following chapter).
- Integrated fails afe wiring and 150  $\Omega$  termination.
- 2. Interface "2A (2D+)", "2B (2D-)" for MODBUS Slave applications
- Connection of the device to a superordinate building control system.
- Setting of address and communication parameters Programming: Menu group MODBUS Slave.



Connection MODBUS Slave and MODBUS Master interface

When using telephone flex with four cable cores, we recommend the following allocation:

- A (D+) = red
- B (D-) = black
- ID ID1/2 = yellow (for automatic addressing for MODBUS Master)
- GND = white

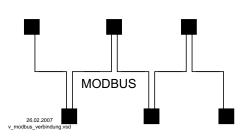


#### Information

- You must ensure correct connection; i.e. "A (D+)" must also be connected on the following devices to "A (D+)". The same applies to "A (D+)".
- Inaddition,a "GND" connection must be established, as dissimilar potential (over 10 V!) will lead to the destruction of the RS-485 interface (e.g. lightning).
- Except for the data link "A (D+)", "B (D-)", the "ID1 ID2" (automatic addressing for MODBUS Master) and the "GND" connection, no further cable cores of the data line may be used.
- Do not use wire shield!
- Pay attention to sufficient distance from powerlines and motor wires (min. 20 cm).

The data line must be connected from one device to the next. No other type of wiring is allowed! Always use only two wires of one lead (twisted pair) for the connection.

**MODBUS** connection



#### Recommended wire types

- 1. CAT5 / CAT7 cables
- 2. J-Y (St) 2x2x0.6 (telephone wire)
- 3. AWG22 (2x2 twisted pair)

Max. allowed wire length 1000 m (CAT5/7 500 m)



#### Information

If any matters are unclear, please contact our V-STE support department for control systems - ventilation technology. The information sheet "Network structure of MODBUS" R-TIL08\_01 contains detailed information about "MODBUS".

#### 5.9.1 Addressing member MODBUS Master Interface

Up to 32 members can be connected at the MODBUS Master interface.

No other components are required for the patented automatic addressing (activation @ menu group MODBUS Master: AutoAddressing). Only the connections "ID1" and "ID2" of the Slave members are connected additionally next to the bus connection and at the "ID" connection of the MODBUS Master for this.

The "ID" connection of the MODBUS Master must be connected to the "ID1" or "ID2" connection of the **first Slave member**. This is recognised as a result and occupied by address **1**.

For the following users the connection "ID1" or "ID2" of a Slave user respectively is connected with connection "ID1" or "ID2" of the next Slave user.

The automatic addressing of other users is initiated by the previous user via this connection. The individual members can be addressed in advance without this device by an external terminal or a

PC.

Alternatively, the addressing can be done manually by a separate hand held terminal or PC software, the appropriate number of members must then be entered on the MODBUS Master ( menu group MODBUS Master: BUS Slavecount).

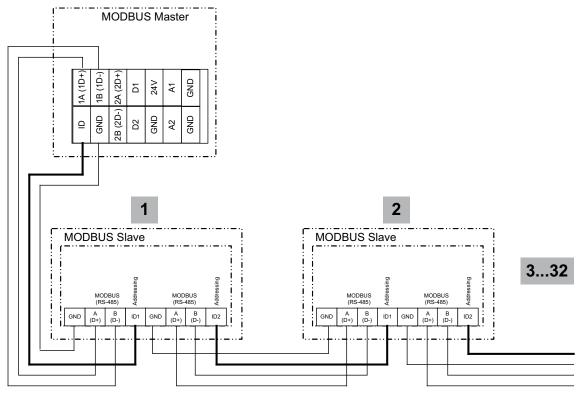


#### Information

- When using the automatic addressing, no repeaters can be used because these do not pass the signal through to the addressing.
- Depending on the version, the connections for MODBUS "A (D+)", "B (D-)" are available single or double at the Slave members. These are connected with each other internally electrically.
- The connections for the automatic addressing "ID1" and "ID2" are **not directly** connected with each other internally. These may not be bridged; any order of connection is possible.
- Do not connect the cable screen! When using the connection box, the cable screen of the CAT5 cable is connected internally by an RC element to "PE".
- The communication parameters are fixed @ Programming: Menu group MODBUS Master.



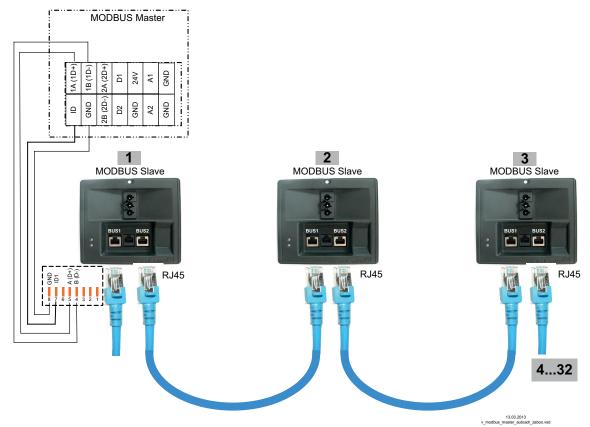
#### Networking with telephone wire



13.03.2013 v\_modbus\_master\_autoadr.vsd

Connection a MODBUS Master via the terminals: 1A (1D+), B (1D-), ID and GND Connection of the Slave members via the terminals: A (D+), B (D-), GND and ID1 / ID2

Networking with RJ45 patch cable by usage connection box for ECblue (part. no. 380085).



Connection to the MODBUS Master at the terminals: 1A (1D+), 1B (1D-), ID and GND Connection of the Slave members via the two RJ45 connections "BUS1" and "BUS2"

#### 5.10 USB-interface

Over the USB interface if necessary a software update can be made. For this a consultation with the manufacturer is necessary.



#### Danger due to electric current

**Plug the jumper J1** to both PINs only for a software update via USB interface. The device will not switch on if this jumper is plugged to both PINs! Do not replug the jumper under voltage, observe the safety instructions!

#### 5.11 Potential at control voltage connections

The control voltage connections (< 50 V) relate to the joint GND potential (Exception: Relay contacts are potential free). There is a potential separation between the control voltage connections and the protective earth. It must be ensured that the maximum external voltage at the control voltage connections cannot exceed 50 V (between "GND" terminals and "PE" protective earth). If necessary, a connection to the protective earth potential can be established, install bridge between "GND" terminal and the "PE" connection (terminal for screening).

## 6 Select operation mode

#### 6.1 Mode and signal input



#### Information

Simple rinstallation is possible through the selection of the preprogrammed mode of operation (Startup).

The purpose of the device is to reach and maintain the target values set. To accomplish this, the measured actual value (sensor value) is compared with the adjusted target value, and the controlled value (modulation) is deduced from this.

By selection of the mode the function for control circuit 1 is determined, this influences the following outputs (factory setting): 1. Analog output "A1" 0 - 10 V with function 2A ( $\Im$  Electrical installation).

2. MODBUS Master interface "1A" + "1B" with function [2A] (@ Electrical installation).

Mode	Signal or Sensor (input)	Function
4.01	Sensor DSG / MPG (E1)	Pressure control for ventilation systems
4.02	1x Sensor DSG / MPG (E1) 1x Sensor KTY81-210 / PT1000 (E2)	Pressure control outdoor temperature compensation (Factory setting)

\* Operation with a second control circuit possible

#### 6.2 Operation with a second control circuit

The function for control circuit 1 is determined by selection of the mode. This influences the output with function  $\boxed{2A}$ .

A second control circuit with separate actual value measuring and separate output can be activated additionally if required.

Control circuit 2 influences the output with function 8A.

- Analog output "A2" (factory setting) IO Setup
- MODBUS Master interface @ member menu

Operation with a second control circuit is **not** possible in the following modes: **4.02** 

The second control circuit is activated by the "E2 function" for the second analogue input "E2" (@menu group "Base Setup").



#### E2 functions for activating control circuit 2:

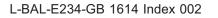
		Factory setting	
E2 Function	Description second control circuit	E2 Analog In	2.Setpoint 1
Temperature (8E)	Temperature control	TF	20.0 °C
Cold-Pressure (9E)	Pressure control condensers	MBG0-30	15.00 bar
Cold-Temperature (10E)	Pressure control for condensers with input for refrigerant	MBG0-30	35.0 °C
Air Pressure (11E)	Pressure control Airconditioning	DSG200	100.0 Pa
Air flow (12E)	Air volume control	DSG200	44720 m <sup>3</sup> h
Air speed (13E)	Air velocity control	MAL1	0.50 m/s

When activating control circuit 2, the "Setting" menu group is extended.

- The additional parameters for control circuit 2 are identified by a prefixed "2." e. g. "2. Setpoint 1".
- A prefixed "1." e. g. "1.Setpoint 1" is added to the parameters for control circuit 1.

#### Example: Second control circuit for temperature control

Operating mode 4.01	for pressure control by control circuit 1
	Temperature control via control circuit 2
Setting	1.Setpoint 1
	Setpoint 1 for control circuit 1
250.0 Pa	Setting range: 0 - 500 Pa
1.Setpoint 1	Factory setting: 250 Pa
Setting	1.Setpoint 2
	Setpoint 2 for control circuit 1
	Setting "Setpoint 2" e.g. reduced value for night operation.
1.Setpoint 2	Switch over Setpoint 1/2 by external contact (as long as no allocation is carried out Display:@ IOSetup).
Setting	1. Pband 1
	Pband 1 for control circuit 1
250.0 Pa	Setting range: 0 - 500 Pa
1. Pband 1	Factory setting: 250 Pa
Setting	1. Min. Speed
	Minimal Speed for control circuit 1
0 %	Setting range: 0 "1. Max. Speed"
1. Min. Speed	Factory setting: 0 %
Setting	1. Max. Speed
	Maximal Speed for control circuit 1
100 %	Setting range: 100 % "1. Min. Speed"
1. Max. Speed	Factory setting: 100 %
Setting	2.Setpoint 1
	Setpoint 2 for control circuit 2
20.0 °C	Setting range with passive sensor type "TF", "PT1000" : -50.0150.0 °C
2.Setpoint 1	Factory setting: 20.0 °C



Setting	2.Setpoint 2		
-	Setpoint 2 for control circuit 2		
	Setting "Setpoint 2" e.g. reduced value for night operation.		
2.Setpoint 2	Switch over Setpoint 1/2 by external contact (as long as no allocation is carried out: — Display:GP IOSetup).		
Setting	2. Pband 1		
	Pband 1 for control circuit 2		
5.0 °C 2. Pband 1	Setting range with passive sensor type "TF", "PT1000": 0.0200.0 K Factory setting: 5.0 K		
Setting	2. Min. Speed		
	Minimal Speed for control circuit 2		
0 %	Setting range: 0 "2. Max. Speed"		
2. Min. Speed	Factory setting: 0 %		
Setting	2. Max. Speed		
	Maximal Speed for control circuit 2		
100 %	Setting range: 100 % "2. Min. Speed"		
2. Max. Speed	Factory setting: 100 %		
Setting	Manual mode		
	Manual mode for control circuit 1		
OFF	"OFF" = automatic control as function of the set parameters (Factory setting)		
1. Manual mode "ON" = automatic control without function, speed setting in menu "S			
	Speed manual		
Setting	opeed manual		
Setting	Speed Manual mode for control circuit 1		
Setting 100 %			

#### Function extension for digital inputs "D1" and "D2" in operation with second control circuit

D1 / D2 Function	Description *
E1 / E2 (4D)	The output for control circuit 2 is set additionally to "A2" to "A1" (regardless of the programmed function for $\boxed{A1}$ ). Control circuit 1 has no output for the duration of the switching.
2. Setpoint 1/2 (9D)	for control circuit 2: Switch over "Setpoint 1" / "Setpoint 2"
2.Setp+Pband1/2 (16D)	for control circuit 2: Switch over Setpoint 1/2 and Pband 1/2 When programming this function, "Setting" additionally lists the parameter: "2.Pband 2 for control circuit 2."

\* Detailed description @ IO Setup / Digital Inputs "D1" / "D2"

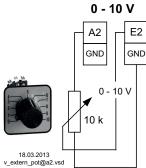
#### Following restrictions apply for the control circuit 2:

- The "Manual Mode" function in the "Setting" menu group only influences control circuit 1!
- The Limit (@ IO Setup 3D and Controller Setup) function influences both control circuits simultaneously.
- The "Max. Speed" setting by a digital input ( ID Setup 11D) simultaneously influences both control circuits. I.e. at "1.Max. Speed" and at "2.Max. Speed".
- The controller configurations (KP, KI, KD, TI @ Controller Setup) are identical for both control circuits. Fine adjustment is possible for each control circuit by the separate "Pband" setting.



#### 6.3 External Setpoint / External speed setting in manual operation

External setpoint setting or external manual operation are possible using a 0 - 10 V (0 - 20 mA, 4 - 20 mA) signal at the "E2" and "GND" terminals. Configure "E2" in Base setup. For potentiometers, program Analog Out 1 (terminal "A1") to the function  $\boxed{1A}$  = "+10 V" (as factory setting  $\bigcirc$  IO Setup). E2 Analog In = factory setting 0 - 10 V



**External Setpoint** via external signal instead of "Setpoint 1". The "external Setpoint" function must be activated in base setup 1E for "E3 function". The active external Setpoint value is displayed in the "info" menu group. **External speed setting** in manual operation. The "external manual operation" function must be activated in the basic settings 2E for "E3 function". Switchover between settings on the device and external manual operation via the digital input (P IO Setup: "Control / manual operation" [7D]).

Not possible in modes with 2 sensors and operation with a second control circuit because the second analogue input is already occupied by it.

## 7 Start-up

#### 7.1 Prerequisites for commissioning



#### Attention!

- 1. You must mount and connect the device in accordance with the operating instructions.
- 2. Double check that all connections are correct.
- 3. The mains voltage must match the information on the rating plate.
- 4. Make sure that no persons or objects are in the fan's hazardous area.



#### 7.2 Procedure for commissioning

- 1. Turn on mains voltage
- Display:



(Function of display (P controls and menu)

- 2. Switch over between "Info" and "Main menu" with the "Esc" key combination
- 3. Menu group: Start
- Set the menu language if necessary (factory setting English = Language GB).
- The display can be switched between SI units (US units = OFF) and imperial (US) units (US units = ON).
- 4. Menu group: Basic setting Set desired operating mode
- 4.01 pressure control, setpoint in Pa
- 4.02 Pressure control setpoint depending on outdoor temperature (factory setting)
- 5. Menu group: Setting
- Set the parameters for the control mode.

#### Excerpt from the menu table

Start			
Language	GB	GB	
US units	OFF	OFF	
Base setup			
Mode	4.01	4.02	
Setting			
Setpoint1	250.0 Pa	250.0 Pa	
Setpoint2	250.0 Pa	250.0 Pa	
Pband 1	250.0 Pa	250.0 Pa	
Min. Speed	0%	0%	
Max. Speed	100 %	100 %	
Manual mode	OFF	OFF	
Speed manual	100 %	100 %	
T-Band SA		30.0 K	
T-Start SA		15.0 °C	
Min Setpoint		70.0 Pa	



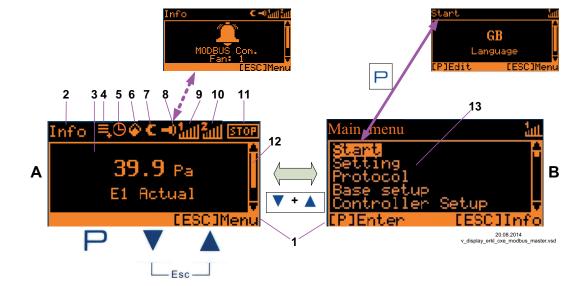
#### Information

Adjust further settings according to the desired function (@ Operating Instructions / Programming)



## 8 Controls and Menu

#### 8.1 Multipurpose LC display and keyboard



Α	Actual value display Display after line voltage is switched on or after the Esc key combination is used to exit the settings menu (display depends on selected mode and sensor value).	<ol> <li>Status bar</li> <li>Display of the menu group in which the displayed menu is located</li> <li>Display window</li> <li>Log entry which still was not seen</li> </ol>
В	Main menu Display after the Esc key combination is used to exit the actual value display. Select the desired menu group with the ▼▲ buttons and use the P-key to open it.	<ol> <li>5. Timer function active</li> <li>6. Fire-Symbol (heating operation)</li> <li>7. Moon-Symbol for set point 2</li> <li>8. Alarm symbol (fault message alternating with actual value display)</li> </ol>
Р	Program key and open menu.	9. Modulation control circuit 1
▼	Menu selection, reduce value.	10. Modulation control circuit 2 (if activated)
	Menu selection, increase value.	11. STOP-Symbol (enable)
▼ + ▲ Esc	<b>Esc</b> -key combination, Escape = leave menu. Switch between Info and Main menu.	<ol> <li>Position of the menu in the menu group</li> <li>List of the menu groups</li> </ol>



#### 8.2 Menu operation

Info	Display after turning on the mains voltage description for menu language English = "GB" (de- livery status). Switch over between "Info" * and "Main menu" with the Esc key combination.	Main menu	
0.0 Pa E1 Actual		Start Setting Protocol Base setup	
		Controller Setup	
[ESC] Menu		[P] Enter	[ESC] Info

Main menu		
Start		
Setting		
Protocol Base setup		Select the desired menu group with the ▼ ▲ keys (text highlighted) and open with the P- key.
[P] Enter	[ESC] Info	

#### 

Start		
	PIN input	PIN input, e.g. for resetting to basic factory setting
[P] Edit	[ESC] Menu	

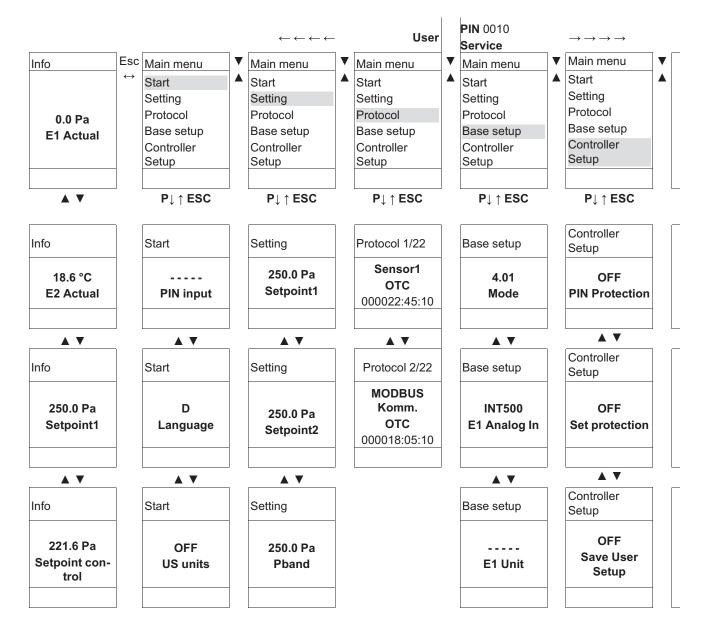
#### 

Start		
		In the menu point "Language" display language can be selected. One returns to the menu group "Start" using the Esc ( $\nabla + \blacktriangle$ ) shortcut keys.
[P] Edit	[ESC] Menu	

## 8.3 Example for programming mode **4.01** in "Base setup "

#### Sequence 2 6 3 5 7 1 4 Base setup Base setup Base setup Base setup 4.02 4.02 4.01 Ρ Ρ 4.01 Mode Mode Mode Mode [P] [ESC] [P] [ESC] [P] [ESC] [P] [ESC]

#### 8.4 Menu structure



#### Menu dependent on mode

Selection of the menu group (e.g. Base setup) to the right through the ▼-key, to the left through the ▼-key.

You can go to the menu items in the menu groups (e.g. mode of operation) by using the **P** key. Use the arrow keys to move up and down within the menu group.

The menu groups consist of one area for the user (user menu) and one area for installation (service). The service area can be protected against unauthorized access by using a PIN.

In order to simplify the initial start-up operation, the service level is enabled at first (i.e., not protected by the PIN 0010 ( Operating Instructions / Controller Setup, PIN protection = OFF). If PIN protection is activated (ON), the service menu remains enabled after input of PIN 0010 as long as one is pressing keys. If no keys are pressed for ca. 15 minutes, the PIN is automatically erased, i.e. the service level is blocked.

To make adjustments, press the **P** key after selecting the menu item. If the previously set value starts to ash, it can be adjusted with the  $\nabla + \Delta$  keys and then saved with the **P** key. To exit the menu without making any changes, use the "Esc" short-key, i.e., the originally set values remain.



#### Information

After installation of the device has been carried out, PIN protection should be activated ( Operating Instructions / Controller Setup)!



#### 8.5 Overview menu groups

Main menu	Possible settings
Info	Display measured actual values, selected setpoints, modulation, etc. Settings cannot be made in this menu group.
Start	PIN input for reset to initial settings and to protect settings. Setting the menu language. Display in SI units or Imperial units (US) Complete re-start of the device. Display of the set mode, software version, etc.
Setting	Settings for Operation, Setpoint, Pband, Min. Speed, Max. Speed, etc.
Protocol	Display and query of events / malfunctions.
Base setup	Setting of the desired mode, configuration of signal and sensor inputs. Activation control circuit 2.
Controller Setup	Activate set protection, save user settings. Activate alarm message in the event of a sensor fault. Activate limitation of modulation via digital input or timer of time switch. Configuration of control parameters, group control.
IO Setup	Configuration and function assignment for: analogue outputs, digital inputs, relay outputs. Function MODBUS interface: COM2 for MODBUS Slave or MODEM SMS.
Limit	Limit messages depending on modulation, setting signal or sensor signal, offset to setpoint.
Timer	Integrated time switch with programmable timer functions. Clock fine adjustment
Diagnostic	Current operating states of the device.
MODBUS Slave MODBUS SMS	Addressing and configuration of the MODBUS Slave interface. alternatively Input of SIM PIN for MODBUS SMS interface (currently no function).
MODBUS Master	Start automatic addressing of members. alternatively Manual input of number of members.



## 9 Programming

This chapter lists some operating modes which cannot be set for the present device type!



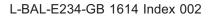
#### Display in SI units or Imperial units (US)

The following description is for display in SI units (factory setting). The appropriate conversion factors must be observed when switching over to Imperial units (US) (@ menu group Start / US Units).

### 9.1 Pressure control airconditioning 4.01... 4.02

#### 9.1.1 Base setup 4.01 ... 4.02

Main menu	Base setup
Start	
Setting	
Protocol	
Base setup	
Controller Setup	
Base setup	Mode Mode selection e.g. 4.01
4.01	
Mode	
Base setup	E1 Analog In
INT500	"E1 Analog In" factory setting for internal pressure sensor with measuring range 500 Pa preprogrammed.
E1 Analog In	If the internal sensor is exchanged against a sensor with other measuring range, which is technically compatible, then the measuring range must be adapted.
	<ul> <li>Other settable sensors / measuring ranges:</li> <li>"DSG 50", "DSG100", "DSG200", "DSG300", "DSG500", "DSG1000", "DSG2000", "DSG4000", "DSG6000", INT300, INT300 (numerical data ≙ measuring range [Pa], output signal 0 - 10 V). Type designation DSG ≙ pressure sensor with new type designation MPG</li> <li>0 - 10 V, 0 - 20 mA, 4 - 20 mA (for sensors with free measuring range and linear characteristic)</li> </ul>
	The sensor measuring range must be entered for sensors with free measuring range in order to display the actual value correctly. Example with a 0 - 10 V sensor and 0 - 400 Pa measurement range: E1 Analog In = 0 - 10 V, E1 Unit = Pa, E1 Decimals = 1, E1 Min. = 0,0 Pa, E1 Max. = 400 Pa
Base setup	E1 Offset
	Sensor calibration with calibrated comparison device.
0.0 Pa	The current "E1 Actual" is displayed including the offset set here.
E1 Offset	





Base setup	E2 Function
	The second signal input is not activated at the factory for modes with one sensor.
OFF E2 Function	The function is automatically jointly programmed in operating modes using two sen- sors. The second analog input is thus allocated and additional function allocations are not possible.
	Modes with two sensors
	<ul> <li>For 4.02 E2 Function at 6E preprogrammed = sensor for setpoint lowering. Preprogrammed sensor type "TF "</li> </ul>
	Adjustable "E2 function" for modes with one sensor
	<ul> <li>IE = External setpoint e.g. by external signal (0 - 10 V) instead of setting "Setpoint 1". 0 - 10 V ≙ 0 - 100 % sensor measuring range.</li> </ul>
	<ul> <li><u>[2E]</u> = External manual operation via external signal (0 - 10 V). Switching between setting on the device and external manual operation via digital input (@ IO Setup: Function [7D]).</li> </ul>
	<ul> <li><u>7E</u> = Measurement value = Measurement value e.g. for limit indication, display in Info menu "E2 Actual".</li> </ul>
	<ul> <li>8E 13E = sensor input for control circuit 2 ratio base setup / operation with second control circuit.</li> </ul>

#### 9.1.2 Setting for operation modes 4.01... 4.02



Pressure control, Setting Setpoint in Pa

2 Pressure control setpoint depending on outdoor temperature

Settings for controller output with function 2A (by analogue signal @ IO Setup, by MODBUS @ members menu).

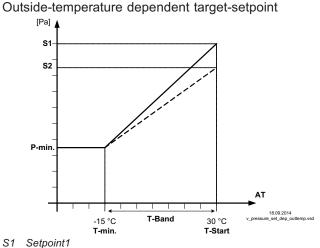
Main menu	Setting
Start	
Setting	
Protocol	
Base setup	
Controller Setup	
Setting	Setpoint1
	Setting range: in measuring range of sensor
250 Pa	Factory setting: 250 Pa
Setpoint1	
Setting	Setpoint2
	Setting "Setpoint 2" e.g. reduced value for night operation.
	Switch over Setpoint 1/2 by external contact (display as long as no allocation is carried
Setpoint2	out: @ IO Setup).
Setting	Pband
	Narrow control range = Short control times
250 Pa	Wide control range = Longer control times and more stable control
Pband	Setting range: in measuring range of sensor
	Factory setting: 250 Pa
Setting	Min. Speed
	Setting range: 0 "Max. Speed"
0 %	Factory setting: 0 %
Min. Speed	
Setting	Max. Speed
	Setting range: 100 % "Min. Speed"
100 %	Factory setting: 100 %
Max. Speed	





Setting	Manual mode
	"OFF" = automatic control as function of the set parameters (Factory setting)
OFF	"ON" = automatic control without function, speed setting in menu "Speed manual"
Manual mode	
Setting	Speed manual
	Manual speed setting without influence by the external signal.
100 %	Activation by menu "Manual mode" or external contact at digital input ( Plo Setup).
Speed manual	Setting range: 0100 % ≙ "Min. Speed" "Max. Speed"
	Factory setting: 100 %
	For information about deactivated regulation the adjusted value for manual speed is indicated alternating with the actual value.

#### Additional menu item for mode **4.02** with outside-temperature dependent target-setpoint.



An outside temperature compensation can be activated (sensor connection "E2" = "Analog In 2") when being operated as a pressure regulation device.

An optimal building climate, e.g., can be achieved through this. Through this function, the set and active "Setpoint1" or "Setpoint2" is automatically changed proportional to the measured outside temperature (@ Info: "Setpoint control").

S1 Setpoint1 S2 Setpoint2 P-min. Minimum pressure T-min Minimum temperature T-Start Setpoint reducing will start below this outside temperature T-band Temperature range AT Outdoor temperature

Setting	T-Band SA
	Temperature range in which the setpoint change continiously with outside temperature
30 K	Setting range: 0.0+100.0 K
T-Band SA	Factory setting: 30.0 K
Setting	T-Start SA
	Setpoint reducing will start below this outside temperature
15 °C	Setting range: -10.040.0 °C
T-Start SA	Factory setting: 15.0 °C
Setting	Min. Setpoint
	Minimum pressure for very low outside temperature
70.0 Pa	Setting range: in measuring range of sensor
Min. Setpoint	Factory setting: 70 Pa





### 9.2 Menu group Start

Main menu	Start
Start	
Settings	
Protocol	
Base setup	
Controller Setup	
Start	PIN input
	The service menu for the installation can be protected against unintentional changes
PIN input	by a pin code. With further pin codes putting back to pre-setting is possible.
	PIN 0010
	Opening service menu, if PIN-protection activated.
	PIN 1234
	Opening "setting".
	if "set protection" = "ON" (@ Controller Setup)
	PIN 9090
	Restore user setting.
	PIN 9091
	Save user setting (corresponds function "Save user setup" = "ON" Controller Setup)
	PIN 9095
	Restore factory setting = delivery status
	Exception:
	The stored events in the "Protocol" menu are retained after resetting to factory setting!
Start	
	Language Menu language by the factory set to English.
GB	In this menu different national languages can be selected (GB = English, D = German
Language	
	US Einheiten
OFF	The display can be switched between SI units and imperial (US) units =>US units ON.
US Einheiten	SI units (factory setting): °C, bar, Pa, m <sup>3</sup> /h, K-Factor, m/s
05 Einneiten	Imperial (US) units: °F, psi, in.wg, cfm, K-Faktor US, ft/s
	Settings for temperature differences (with SI units in K) are also made for Imperial units
	(US) in °F ( $\Delta$ 1.8 °F $\triangleq \Delta$ 1 K).
	Conversion factors:
	• Temperature: t / °F = 1,8 x t °C + 32.
	• Pressure: 1,0 psi = 0,069 bar, 1,0 in.wg = 254 Pa
	• Air flow: 1,0 cfm = 0.5885 m <sup>3</sup> /h, inlet ring: K-Factor US = 9,3 x K-Factor SI
	• Speed: 1.0 ft/s = 0.3048 m/s
	In order to refresh the display, the desired mode must be confirmed again after switch-
	ing over the units (@ Base setup)!
Start	Reset
OFF	Complete re-start of the device
Reset	
Start	Mode
1.01	Query of the operating mode (e.g. <b>1.01</b> for speed controller)
Mode	
Start	Device name
9.15	Display of device name and software version
ххх	



Start	Individual unit number
SN: 154036311039	

## 9.3 Menu group Info

	ne Info menu group is displayed (display dependent on selected mode) after switching on
-	exiting the setting menu with the Esc key combination.
Settings cannot be mad	ie in this menu group!
Info	Current actual value measured on the sensor 1
0.0 Pa	
E1 Actual	
Info	Display for "actual value 2" for operation with two sensors.
0 °C	Display if function not active: []
E2 Actual	
Info	Display of the active target value at which the device operates.
250.0 Pa	"Setpoint1" Menu "Setting"
Setpoint1	"Setpoint2" Menu "Setting"
	<sup>4</sup> "Ext. Setpoint" = setting by external signal 0-10 V. With activated manual mode the display constantly changes between actual value and value for manual mode.
	Display for operation with two control circuits:
	"1.Setpoint 1" or "1.Setpoint 2" for control circuit 1
	"2.Setpoint 1" or "2.Setpoint 2" for control circuit 2
Info	Only for mode <b>4.02</b> , with setpoint depending on outdoor temperature (E2 function =
100.0 Pa	<u> </u>
Setpoint control	_
Info	Level modulation control output.
0 %	In addition to the bar chart, the level of the output voltage is indicated.
Modulation	
	The modulation for each control circuit is displayed in operation with two control circuits:
	"1. Modulation" for control circuit 1
	"2. Modulation" for control circuit 2
Info	Momentarily status for minimum speed cut off
OFF	"ON" = switch off, if Setpoint (+/- "Min. speed cut off") is reached.
Min. speed cut off	"OFF" = no switch off that means operation with minimum rate of air.
	Display for operation with two control circuits:
	"1. Min. speed cut off" for control circuit 1
	"2. Min. speed cut off" for control circuit 2



#### 9.4 Controller Setup

#### 9.4.1 PIN protection activate, PIN 0010

Controller Setup	The adjustments for the installation in the service level can be protected against
OFF	unintentional modifications. To do this, activate the "PIN protection" = "ON". In order to simplify the initial start-up operation, the service level in the factory setting is free = "OFF" i.e. accessible without <b>PIN 0010</b> .

#### Available menu groups with activated PIN-protection

Main menu
Start
Setting Protocol
Protocol

If PIN-protection is switched on, it automatically becomes active after about 15 minutes without keys being pressed.

#### Possibilities for early activation of PIN protection:

- Execute the "Reset" function in the "Start" menu group.
- By switching the mains voltage off and then on again.



#### Information

After installation of the device has been carried out, "PIN-Protection" should be activated = "ON"

#### 9.4.2 PIN protection activate, PIN 1234

Controller Setup	The "Settings" menu for the user's basic settings (Setpoint, default value, min, max)
	are freely accessible when using the factory settings (i.e. without "PIN").
OFF Set protection	If necessary, these can also be protected against unauthorized modifications by using a " <b>PIN 1234</b> ". For this, the settings protection must be programmed to "ON". The settings menu is then no longer visible without inputting a PIN!
	Function only in combination with activated PIN-Protection!

#### Available menu groups with activated PIN-protection + setting protection

#### 9.4.3 Save user settings restore with PIN 9090

Controller Setup	The individually made device configurations (User Setting) can be saved here (corresponds to PIN 9091).
OFF Save User Setup	By entering <b>PIN 9090</b> the individually made device configurations can be reestablished ( The Start - PIN Input).
	A file (userconf.csv) is generated and saved on the main drive (root directory) when saving the user setting. The data can be accessed via the <b>ZAset</b> program.





#### Information

By entering the "PIN 9095" in the "PIN" menu of the "Start" menu group the device is reset to the asdelivered state (except for the saved events in the "Protocol"menu). Any changes that have been made to the settings are thus lost.

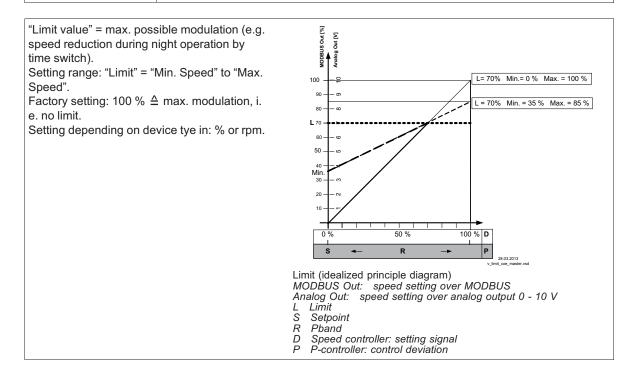
#### 9.4.4 Sensor Alarm ON / OFF

The inputs "E1 Analogue In" and if Sensor 2 is activated "E2 Analogue In" are monitored. In case of an interruption or short-circuit in the sensor conductor, or in case of measured values that lie outside of the device's measurement range, a time-delayed fault indication takes place. Function only in controller mode (from **2.01**)!

Controller Setup	With "Alarm Sensors" = "ON" (factory setting). Indicated	
ON	sensor disturbances are displayed as "Alarm" alternating to the actual value and stored in the menu of "Protocol".	
Alarm sensors	A programmed alarm relay (factory setting relay K2) indicates the sensor failure.	Sensor 1
Controller Setup	With "AlarmSensors" = "OFF" areindicated sensor disturban-	
OFF Alarm sensors	ces as "Message" alternating to the actual value and stored in the menu of "Protocol".	Sensor 1

#### 9.4.5 Limit

Controller Setup	After allocation of a digital input (@ IO Setup) an adjustable limitation of the modulation
	can be activated via a digital input ("D1", "D2",).
	Display as long as no allocation has been carried out in "IO Setup":
Limit	The limitation influences both outputs in operation with two control circuits.





#### 9.4.6 Minimum speed cut off

Controller Setup	This function is primarily significant for installation of the device as a pure P Controller
	in refrigeration and air-conditioning technology.
OFF	For operation mode speed controller <b>1.01</b> without function!
Min. speed cut off	
	Display for operation with two control circuits:
	"1. Min. speed cut off" for control circuit 1
	"2. Min. speed cut off" for control circuit 2

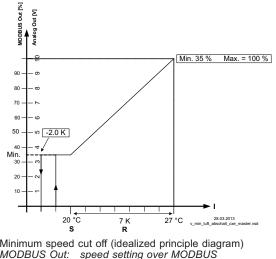
#### Msco = OFF (factory setting)

If no "Min. speed" is adjusted, the fan stops with reaching the desired value. If "Min. speed" is adjusted (e.g. 20%), then no disconnection of the fan takes place. I.e., always a minimum ventilation is ensured (fan does not go under setting "Min. speed").

#### Msco. e.g. -2.0 K

It takes place a disconnection from setting "Min. speed" to "0", if the given difference is reached related to the desired value.

At a plus value (+) before reaching the desired value At a minus value (-) after falling below the desired value.



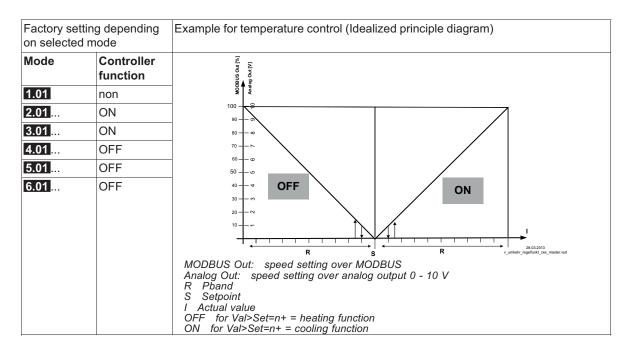
Minimum speed cut off (idealized principle diagram) MODBUS Out: speed setting over MODBUS Analog Out: speed setting over analog output 0 - 10 V S Setpoint R Pband I Actual value

#### 9.4.7 Reverse action of the control function

Controller Setup	For the effect of the regulation there are two functions:
ON Val>Set=n+	<ul> <li>ON for "Val&gt;Set=n+" △ increasing Fanlevel for increasing actual value over Setpoint.</li> <li>OFF for "Val&gt;Set=n+" △ increasing Fanlevel for decreasing actual value below Setpoint.</li> </ul>
	Display for operation with two control circuits: "1. Actual>Set=n" for control circuit 1 "2. Actual>Set=n" for control circuit 2 For special applications an external switch over of the control function is possible (@ IO Setup).







#### 9.4.8 Controller configuration

The "controller configuration" is automatically carried out during selection of the application related mode of operation (Base setup). The factory presets in accordance with the mode of operation are based on many years of experience, which is suitable for many applications. Under special circumstances, these can be individually adapted (P Menu group "setting").

Controller Setup	The type of control determines the method with which the controlled value behaves in
	case of a difference between the target and current values. For this, the control
Р	technology has standard algorithms, which consist of a combination of three methods:
Type of control	Selection P, PID:
	• P control (Proportional component, proportion of the absolute deviation)
	I control (Integral component, proportion of the sum of all deviations)
	• <b>D</b> control (Differential component, proportion of the last difference)
	Display for operation with two control circuits:
	"1.Controller type" for control circuit 1
	"2.Controller type" for control circuit 2
With pure P controller	s (controller type <b>P</b> ), the following described settings do not have any function.
Ŭ	tion (KP, KI, KD, TI) is identical for both control circuits in operation with two control circuits. ssible for each control circuit by the separate "Pband" setting.
Controller Setup	P-component = reaction time
	Setting range: 0 - 200 %
50 %	smaller = more slowly
КР	bigger = faster
Controller Setup	I-component = accuracy, correction time
	Setting range: 0 - 200 %
50 %	bigger = faster
ĸı	smaller = more slowly



Controller Setup	D-component
50 % KD	<ul> <li>More "D-component" causes more stability by a clean actual value signal with shorter correction times</li> <li>By a actual value signal with a superposition should be done to attitude without "D-component" → 0 %</li> <li>Setting range: 0 - 200 %</li> <li>value smaller = less "D-component"</li> <li>value higher = more "D-component"</li> </ul>
Controller Setup	Integration time = correction time
0 % TI	Setting range: 0 - 200 % smaller = faster bigger = more slowly

#### 9.4.9 Group control

Fan groups can be activated by the analogue outputs "A1" and "A2", the relay outputs "K1" and "K2" or by the RS-485 interface for MODBUS RTU.

Controller Setup	Setting range 0 / 1
	Following group versions are available:
0	• <b>0</b> : One controlled group and up to three switched groups (factory setting)
Group version	• 1: Two controlled groups

#### Group control via analogue outputs and relays

- The groups must be connected at the appropriate programmed output when activating by the analogue outputs and relays.
- The assignment of the analogue outputs and the relays for the group control takes place in the IO Setup.
- The number of possible groups depends on the available hardware outputs in the MODBUS Master (maximum of 4 groups possible).

#### Group control im MODBUS Master Operation

- If controlling via MODBUS, an individual function can be programmed for each group device.
- The virtual outputs are assigned after the menu group "MODBUS Master" for the respective component "fan 1".."fan xx".
- The number of possible groups does **not depend** on the available hardware outputs in the MODBUS Master (maximum of 4 groups possible).

Group functions (@-IO Setup)

Analog output A1, A2 MODBUS A1, A2 2A = Group 1 5A = Group 2 11A = Group 3 12A = Group 4

Relay output K1, K2

8K = Group 2 12K = Group 3 13K = Group 4



#### Information

- Group activation by analogue output, relay and MODBUS can also be combined.
- Ensure an ascending and complete sequence when assigning the groups. This means that if, for example, the function for a fourth group was assigned for an output, there must already be an assignment for groups 2 and 3 (P IO Setup).
- The group control only becomes active once a group function is allocated to an output (analogue, relay, MODBUS).



#### 9.4.9.1 Variant "0": One controlled group and up to three switched groups

The programming described below applies equally for group control by analogue outputs, relay outputs and MODBUS.

For group control by the analogue outputs "A1" / "A2" and the relay outputs "K1" and "K2", the available outputs must be observed in the selection of the version (combinations are possible).

#### Example: Required assignment for a controlled and a switched group

- For activation by analogue output (@ IO Setup) or MODBUS (@ MODBUS Master)
  - Function A for group 1 (0 100 % controlled)
  - Function 5A for group 2 (0 / 100 % switched)
- For activation of Group 2 by relay (P IO Setup)
  - Function A for group 1 (0 100 % controlled)
  - Function 8K for group 2 (ON / OFF switched)

The function 11A must be allocated additionally to Group 3 for one controlled and two switched groups.

The function 12A must be allocated additionally to Group 4 for one controlled and three switched groups.

Controller Setup	Group 2 ON value
	Switch-on value for Group2
50 %	Setting range: 0 - 100 %
Group 2 ON value	Factory setting: 50 % *
· · ·	
Controller Setup	OFF Value Group2
	Switch-off value for group2
45 %	Setting range: 0 - 100 %
OFF Value Group2	Factory setting: 45 % *
Controller Setup	nmin at Group2
	 Minimum Value for Group2
20 %	Setting range: 0 - 100 %
nmin at Group2	Factory setting: 20 % *
Controller Setup	Group 3 ON value
	Switch-on value for Group3
70 %	Setting range: 0 - 100 %
Group 3 ON value	Factory setting: 70 % *
Controller Setup	OFF Value Group3
	Switch-off value for group3
65 %	Setting range: 0 - 100 %
OFF Value Group3	Factory setting: 65 *
Controller Setup	nmin at Group3
· ·	 Minimum Value for Group3
30 %	Setting range: 0 - 100 %
nmin at Group3	Factory setting: 30 % *
Controller Setup	Group 4 ON value
	Switch-on value for Group4
OF 0/	Setting range: 0 - 100 %
85 % Group 4 ON value	Factory setting: 85 % *
Group 4 Ora value	



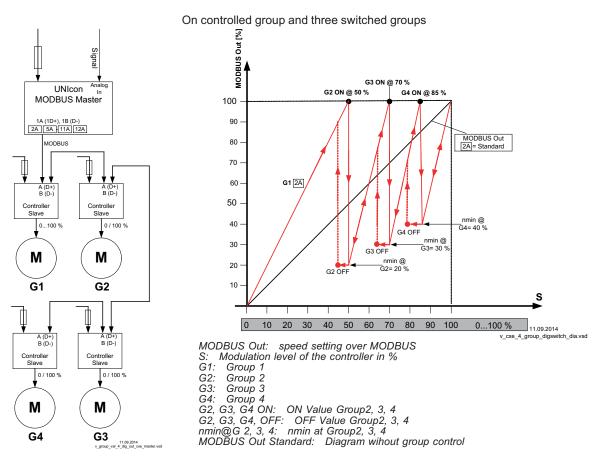


OFF Value Group4
Switch-off value for group4 Setting range: 0 - 100 % Factory setting: 80 % *
nmin at Group4
Minimum Value for Group4 Setting range: 0 - 100 % Factory setting: 40 % *
-

\* Display as long as no group assignment via analogue output, relay, MODBUS: ----

Higher settings must be selected for following groups and the switch-off value of the group must be below the switch-on value.

#### Example version "0" via MODBUS



#### Function

Group 1 is continuously controlled (0 - 100 %), the other groups are switched on and off depending on the degree of modulation (0 / 100%).

If the modulation level exceeds the switch-on point "ON Value Group2", the MODBUS Master switches on the second group and the speed of the first group is reduced to an adjustable minimal value "nmin at Group2".

Then the speed of the first group increases to maximum within the remaining range.

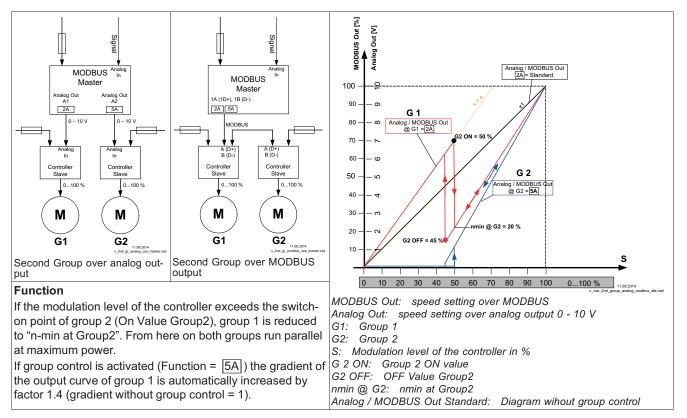
If a third group is programmed up to switch-on point "ON Value Group3" etc.

Switch-off point "OFF Value Group2" at diminishing speed requirement.



Controller Setup	Group 2 ON value
50 % Group 2 ON value	Switch-on value for Group2 Setting range: 0 - 100 % Factory setting: 50 % *
Controller Setup	OFF Value Group2
	Switch-off value for group2
45 %	Setting range: 0 - 100 %
OFF Value Group2	Factory setting: 45 % *
Controller Setup	nmin at Group2
	Minimum Value for Group2
20 %	Setting range: 0 - 100 %
nmin at Group2	Factory setting: 20 % *

\* Display as long as no group assignment via analogue output, relay, MODBUS: ----



#### Example version "1": Two controlled groups



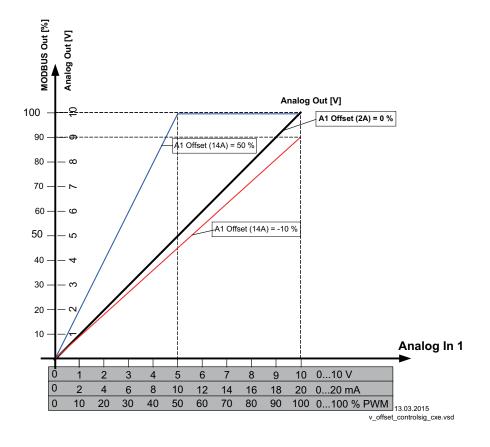
#### 9.4.10 Display text for external message

Controller Setup	Alternatively to the "External Error" display when an external message occurs ( PIO
<b>External error</b> External message	<ul> <li>Setup / Digital Inputs "D1" / "D2" the following error texts can be programmed:</li> <li>EC Motors</li> <li>Filter</li> </ul>
	<ul> <li>Frost protection</li> <li>Adiabatik</li> <li>Firealarm</li> </ul>
	<ul> <li>Pressure switch</li> <li>Gas alarm</li> <li>Water alarm</li> <li>RCD</li> </ul>

RCD Residual-current-operated protective device

#### 9.4.11 Offset control signal

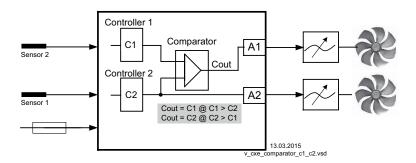
Controller Setup	Offset control sig. 1
0 % Offset control sig. 1	If required, the characteristic of the control signal for control circuit 1 can be adjusted. To activate this function, re-program the output with function 2A to function 14A. IO Setup. Setting range: 0 - 50 % Factory setting: 0 % (characteristic curve unchanged)





#### 9.4.12 Selection amplifier (comparator) control circuit 1 or 2 at output A1

Controller Setup	If using two control circuits, the control circuit with the higher modulation can be selected to affect the power component of the device.
OFF Selection amplifier	This function can be used for refrigeration systems with combined refrigerant circuit and floating brine pressure control circuits, for example.
	Example:
	• Control circuit 1 is used for the refrigerant circuit. A pressure sensor is connected to determine the actual value. The setpoint and control range are set in bar.
	<ul> <li>Control circuit 2 is used for the brine pressurised circuit. A temperature sensor is connected to determine the actual value. The setpoint and control range are set in C° / K.</li> </ul>
	• Depending on which control circuit produces the higher modulation (depending on the measured and set values), the pressure control or temperature control is used as a specification for the power component.
	Selection amplifier = OFF (factory setting)
	No comparison of the two control circuits.
	Selection amplifier = ON
	Comparison of the modulation of control circuit 1 and control circuit 2 with automatic control active at the highest value.



#### 9.4.13 Data on the total control deviation

The total control deviation is comprised of the sum of the control deviations for performance quantities and work quantities combined and refers to the specified areas.

In direct reference to the acquired input and controlled variables, the maximum deviation to the target value is  $< \pm 5$  %. By activating the menu-assisted adjustment, the total control deviation can be reduced to a value of  $< \pm 1$  %.

For indirect reference of the acquired input value to the controlled variable, i.e., two physical variables still need to be converted, the deviation can be reduced to  $< \pm 5$  % through adjustment.

In the case of an internal default value through the integrated or external terminal, the control deviation remains at  $< \pm 0.5\%$ .





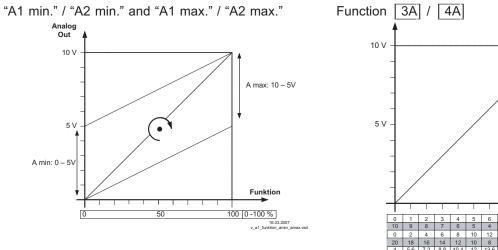
# 9.5 IO Setup

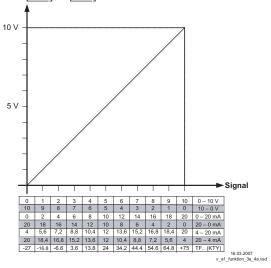
# 9.5.1 Analog outputs "A1"/ "A2"

IO Setup	The analog outputs 0 - 10 V (A1 and A2) can be allocated with various functions.
1. Control signal (2A) A1 Function	
IO Setup	With the settings "A1 min." / "A2 min." and "A1 max." / "A2 max." the characteristic of the output voltage can be adapted.
0.0 V A1 min.	Setting range: — "A1 min." / "A2 min." = 0 - 10 V
IO Setup	—"A1 max." / "A2 max." = 0 - 10 V
10.0 V A1 max.	Factory setting: "A1 min." / "A2 min." = 0 V "A1 max." / "A2 max." = 10 V
	The setting for "A1 min." / "A2 min." must be below "A1 max." / "A2 max.".
IO Setup	Inverting of the output voltage is possible with the settings "A1 Inverting" / "A2 Inverting".
OFF A1 Inverting	Factory setting: Inverting = "OFF"

Function	Description
OFF	no function
Constant voltage 10 V	Constant voltage +10 V
(1A)	Factory setting for "A2" at operation with one control circuit.
1st control signal (2A)	Controlled 0 - 10 V output for control circuit 1 (factory setting for "A1")
E1 (3A)	proportional input "E1"
E2 (4A)	proportional input "E2"
Group2 (5A)	Group control (@ Controller Setup - group 2)
2.Cooling	Only for mode <b>2.03</b> temperature controller with additional functions.
(6A)	Controller output 2 with rising activation at Actual>Nominal = <b>Cool</b> .
2.Heating	Only for mode <b>2.03</b> temperature controller with additional functions.
(7A)	Controller output 2 with rising activation at Actual <nominal =="" heat.<="" th=""></nominal>
2. control signal (8A)	Controlled 0 - 10 V output for control circuit 2 (factory setting for "A2" at operation with second control circuit).
	Control circuit 2 can be activated by programming the E2 function if required ( Base setup / operation with second control circuit).
Speed (9A)	proportionally 1.Control signal
Group3 (11A)	Group control (@ Controller Setup - group 3)
Group4 (12A)	Group control (@ Controller Setup - group 4)
Offset control sig. 1	Offset control signal 1
(14A)	Setting offset @ Controller Setup







#### 9.5.2 Digital inputs "D1" / "D2"

#### 9.5.2.1 Menu overview

Possible functions for D1 @ following table.
To invert the function, switch to "ON" (display] as long as no function is allocated for D1).
With networking the digital inputs can be replaced by control over bus (Slave interface
2A/2B). With mode of operation <b>4.03</b> pre-setting of "D1" is ON. If bus mode is at ON, the digital input can be set by coil register c0 for D1.
Possible functions for D2 @ following table.
To invert the function, switch to "ON" (display as long as no function is allocated for D2).
With networking the digital inputs can be replaced by control over bus (Slave interface 2A/2B).





IO Setup	If the digital inputs have the <b>same</b> function allocation (also applies for timer function) you can choose between an AND and OR operation.
OG D - D Relation	<b>OR</b> operation (factory setting). The function becomes active <b>when one</b> of the digital inputs or the timer is activated.
	<b>AND</b> operation. The function becomes active <b>when all</b> digital inputs or also the timer are activated.
Function	Description
OFF	No function (factory setting for D2)
Enable (1D)	Enable (remote control) "ON" / "OFF"
External error (2D)	External fault alarm
Limit	"Limit" ON / OFF
(3D)	Influences control circuit 1 and control circuit 2 in operation with two control circuits
E1 / E2 (4D)	Switch over input "E1" / "E2" (for operation with one control circuit)
Setpoint1/2 (5D)	Switch over "Setpoint 1" / "Setpoint 2" für control circuit 1 (factory Setting for D1)
Setpoint int./ext.	Switch over "Intern" / "Extern"
(6D)	Possible only for operation with one control circuit!
Control/Manual	Switch over "automatic control" / "Speed manual"
(7D)	Possible only for operation with one control circuit!
Heating/Cooling (8D)	Switch over control function (e.g. "heating" / "cooling")
Reset (10D)	Complete re-start of the device
Max. Speed	Setting Max. Speed "ON" / "OFF"
(11D)	Influences the respectively set value "1. Max. Speed" and "2. Max. Speed" in operation with two control circuits.
1.Setp+Pband1/2	for control circuit 1: Switch over Setpoint 1/2 and Pband 1/1
(15D)	When programming this function, "Setting" additionally lists the parameter: "1.Pband2 for control circuit 1."
Override Time	Overwrite timer function (in operation with timer)
(21D)	The timer output is overwritten for a settable time with a selectable status (ON / OFF).
	Only active in operation with a second control sizewit
	Only active in operation with a second control circuit
E1 / E2 (4D)	The output for control circuit 2 is set additionally to "A2" to "A1" (regardless of the programmed function for "A1"). Control circuit 1 has no output for the duration of the switching.
(40)	The switch over input "E1" / "E2" as in operation with one control circuit is no longer possible.
2. Setpoint 1/2 (9D)	for control circuit 2: Switch over "2. Setpoint 1" / "2. Setpoint 2"
2 Sotn+Phand1/2	for control circuit 2: Switch over Setpoint 1/2 and Pband 1/2
2.Setp+Pband1/2 (16D)	When programming this function, "Setting" additionally lists the parameter: "2Pband2 for control circuit 2."



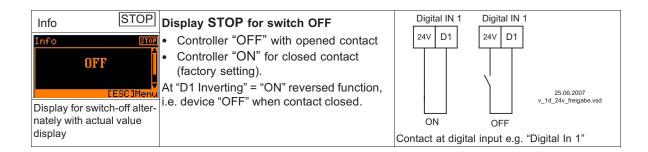
# 9.5.2.2 Enable ON/OFF function 1D

Remote ON/OFF by potential-free contact.

Activation of the members (speed setting) by analogue output and MODBUS interface is switched off, the other signal inputs and outputs stay active.

The device can still be operated in the switched-off state after pressing the "Esc" key combination.

- A programmed operating indicator relay (factory set "K1 function" = 1K) reports the switch-off.
- A programmed alarm relay (factory set "K2 function" = 2K) does not report the switch-off.



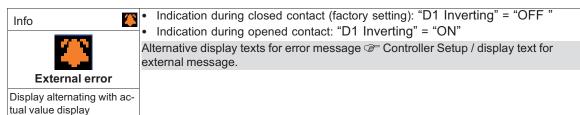


#### Attention!

No disconnection (isolation) when turned off, in accordance with VBG4 §6)!

#### 9.5.2.3 External message, Function 2D

Connecting an external alarm indication (via floating contact). The device continues to work unchanged during an external indication to the digital input; the alarm symbol appears in the display. This indication can be issued via the relay contacts (K1 K2) (P IO Setup function K1, K2).

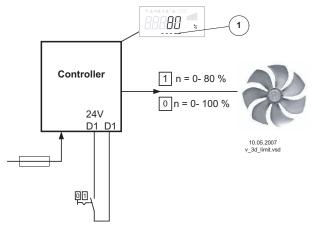


#### 9.5.2.4 Limit ON / OFF, Function 3D

The value for "Limit" adjusted in the Controller Setup, is activated over a digital input. Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").

For "D1 Inverting" = "OFF", limitation active at closed contact.

The limitation influences both outputs in operation with two control circuits.



1 Setting "Limit" (depending on device type in: %, Hz, rpm)

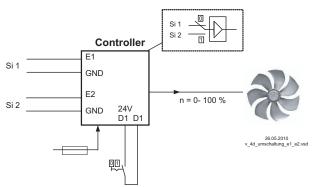


# 9.5.2.5 Switch over input "E1" / "E2", function [4D]

# (operation with one control cicuit)

Switch over between Input signal 1 (Analog In 1 terminal "E1") and input signal 2 (Analog In 2 terminal "E2").

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").



#### Si 1 Signal 1

Si 2 Signal 2

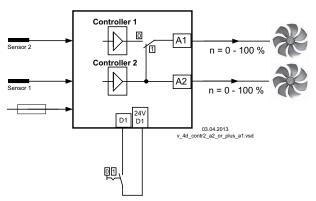
For mode speed controller (**1.01**) Base setup for "E2 Analog In": **1**E necessary. For modes controller (from **2.01**..) Base setup for "E2 Analog In": **7**E necessary (as far as otherwise does not occupy).

#### 9.5.2.6 Output control circuit 2 additional to "A2" on "A1", function 4D

The output for control circuit 2 is set additionally to "A2" to "A1" (regardless of the programmed function for  $\boxed{A1}$ ). Control circuit 1 has no output for the duration of the switching.

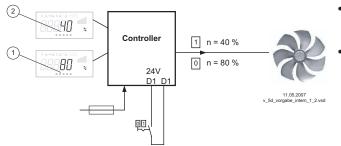
Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").

At "D1" Inverting "OFF" the output of control circuit 2 also influences output "A1" when the contact is closed.



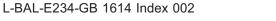
# 9.5.2.7 Set 1/2 or Setpoint 1/2, Function 5D

For Mode Speed controller **1.01**: Switch over "Set Intern1" / "Set Intern2 " Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").

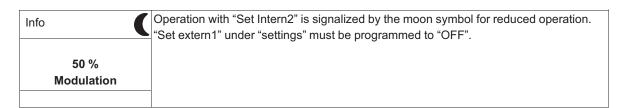


1 Setting "Set Intern1" (depending on device type in: %, Hz, rpm) 2 Setting "Set Intern2" (depending on device type in: %, Hz, rpm)

- "D1 Inverting" = "OFF": "Set Intern1" at opened contact / "Set Intern2" at closed contact.
- "D1 Inverting" = "ON": "Set Intern1" at closed contact / "Set Intern2" at opened contact.

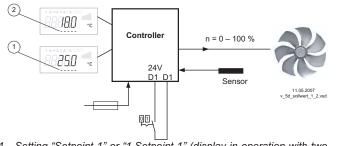






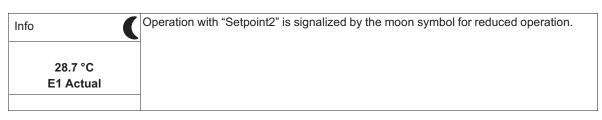
#### For operation as controller (starting from 2.01): switch over "Setpoint 1" / "Setpoint 2" For operation with second control circuit: switch over "1.Setpoint 1" / "1.Setpoint 2"

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" -"24 V").



- "D1 Inverting" = "OFF": "Setpoint1" = 18 °C • at opened contact / "Setpoint2" = 25 °C at closed contact.
- "D1 Inverting" = "ON": "Setpoint1" = 18 °C at closed contact / "Setpoint2" = 25 °C at opened contact.

Setting "Setpoint 1" or "1.Setpoint 1" (display in operation with two 1 control circuits for Setpoint 1 of control circuit 1) Setting "Setpoint 2" or "1.Setpoint 2" (display in operation with two control circuits for Setpoint 2 of control circuit 1) 2

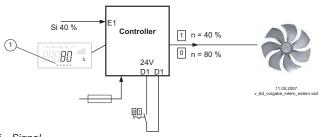


#### Intern / Extern Function 6D 9.5.2.8

#### For Mode Speed controller 1.01: Switch over "Set Intern" / "Set external "

"Set extern1" under settings must be programmed to "OFF".

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" -"24 V").



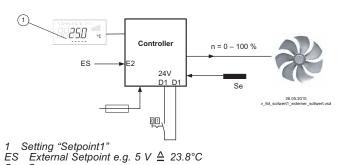
- "D1 Inverting" = "OFF": "Set Intern1" at opened contact / "Setting Extern" at closed contact.
- "D1 Inverting" = "ON": "Set Intern1" at closed contact / "Set Extern" at opened contact.
- Si 1 Signal Setting "Set Intern1" (depending on device type in: %, Hz, rpm)

Se

Sensor

# For operation as controller (starting from 2.01): switch over "Setpoint 1" / "external Setpoint" Possible only for operation with one control circuit!

Under Base setup "E2 function" programmed to function <u>[1E]</u> for "external setpoint". Contact at digital input e.g. "Digital In 1" = "D1" - "D1"



- "D1 Inverting" = "ON": Setting at the unit at opened contact / Signal Extern at closed contact
- "D1 Inverting" = "OFF": Setting at the unit at closed contact / Signal Extern at opened contact

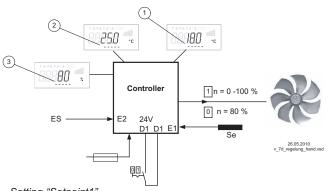
# 9.5.2.9 Automatic control / speed manual Function [7D] (mode 2.01)

Possible only for operation with one control circuit!

Switch over between automatic control to set target value (depending on the activation: "Setpoint1", "Setpoint2") and the default for "manual operation" set at the device.

If for Analog In 2 "E2 function" is programmed to [2E] switch over between "Setpoint1" or "Setpoint2" and external manual operation. With activated manual mode the display constantly changes between "actual value" and value for "manual mode".

Contact at digital input e.g. "Digital In 1"



- "D1 Inverting" = "OFF" Automatic control at opened contact / manual operation at closed contact.
- "D1 Inverting" = "ON": Automatic control at closed contact / manual operation at opened contact.

1 Setting "Setpoint1"

2 Setting "Setpoint2"

3 Setting "Speed manual" (depending on device type in: %, Hz, rpm) EH Signal for Manual mode extern, E2 Function = [2E]

# 9.5.2.10 Reverse action of control function (2.01), Function 8D

Switchover between: Increasing modulation during increasing actual-value and increasing modulation during sinking actual-value.

The factory presets for the "Control function" are dependent on the selected mode of operation ( Controller Setup - reverse operation of the control function).

When switching over via a digital input, the device works with the opposite function as set there. The inversion of the control function influences both circuits in operation with two control circuits.

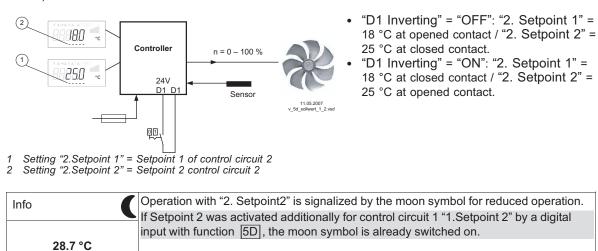
Controller Setup	Settings in Controller Setup
	Display for operation with two control circuits:
ON	"1. Actual>Set=n" for control circuit 1
Val>Set=n+	"2. Actual>Set=n" for control circuit 2
Var Oct-II+	

Se Sensor

#### 9.5.2.11 Switch over Setpoint 1/2 for control circuit 2 9D

Switch over between "2.Setpoint 1" and "2.Setpoint 2" (for operation with two control circuits)

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").



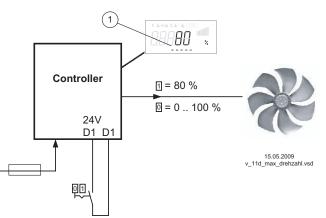
#### 9.5.2.12 Setting Max. Speed ON / OFF function 11D

E2 Actual

The value for "Max Speed" adjusted in menu "Settings", is activated over a digital input. I.e. the unit works independently of the controller function firm with this value.

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").

This function influences both circuits in operation with two control circuits.



- "D1 Inverting" = "OFF": "Max. Speed" active at closed contact
- "D1 Inverting" = "ON": "Max. Speed" active at opened contact

Display depending on device type in: %, Hz, rpm 1 Setting "Max. Speed" or "1.Max. Speed" and "2.Max. Speed" for operation with two control circuits

#### 9.5.2.13 Switch over Setpoint 1/2 and Pband 1/ 2 for control circuit 1 15D

Switching between "1st setpoint 1" / "1st setpoint 2" and "1st Pband 1" / "1st Pband 2" (from **2.01**, not for **2.03**).

Function basically the same as [5D], it is additionally switched over to Pband 2.

When programming this function, "Setting" additionally lists the parameter: "1.Pband 2 for control circuit 2."

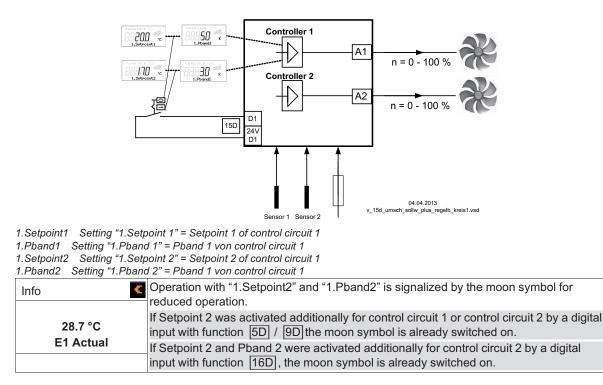
46/84

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").

Example for "D1 Inverting" = "OFF":

- With open contact: "1.Setpoint 1" = 20 °C + "1.Pband 1" = 5 K
- With closed contact: "1.Setpoint 2" = 17 °C + "1.Pband 2" = 3 K





#### 9.5.2.14 Switch over Setpoint 1/2 and Pband 1/2 for control circuit 2 16D

Switch over between "2.Setpoint 1" / "2.Setpoint 2" and "2.Pband 1" / "2.Pband 2" (only for operation with second control circuit possible).

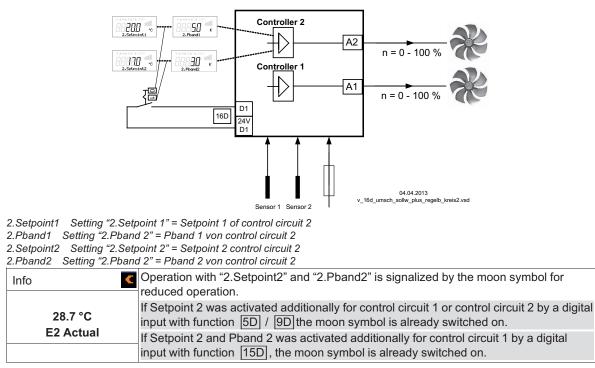
Function basically the same as [5D] and [9D], it is additionally switched over to Pband 2.

When programming this function, "Setting" additionally lists the parameter: "2Pband2 for control circuit 2."

Contact e.g. at ditgital input "Digital In 1" (depending on device type at terminals "D1" - "D1" or "D1" - "24 V").

Example for "D1 Inverting" = "OFF":

- With open contact: "2.Setpoint 1" = 20 °C + "2.Pband 1" = 5 K
- With closed contact: "2.Setpoint 2" = 17 °C + "2.Pband 2" = 3 K



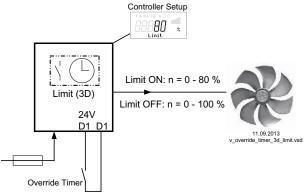


#### 9.5.2.15 Timer function overwrite 21D

The timer output can be overwritten for a settable time with a selectable status if required (@ timer). To overwrite the timer function by pressing keys until the next timing change => "Override Time" = 0 min.

The override time is activated by pressing a key at a digital input (example for D1 not inverted). The bypass time can be ended prematurely by pressing another key.

If the contact remains closed, the override time also run out, then a short interruption is required to reactivate.



Contact depending on device type at terminals "D1" - "D1" or "D1" - "24 V"

Example: speed limitation over Timer (Function 3D)

The timer limits the maximum speed for a certain period of time (e.g. timer ON from 6:00 - 10:00 am). With the "Override Timer" contact the limitation (from 6:00 - 10:00 am) activated by the timer can be cancelled for an adjustable period "Override Time" ( timer / timer function overwritten: Override Status = OFF)

To activate the limitation outside the programmed time (10:01 - 5:59 am) => "Override Status" = ON

#### 9.5.3 Configuration of analog inputs "E1" and "E2"

#### 9.5.3.1 Signal adaption E1 and E2

If required, an adaptation of the specification signal / speed characteristic curve is possible



#### Information

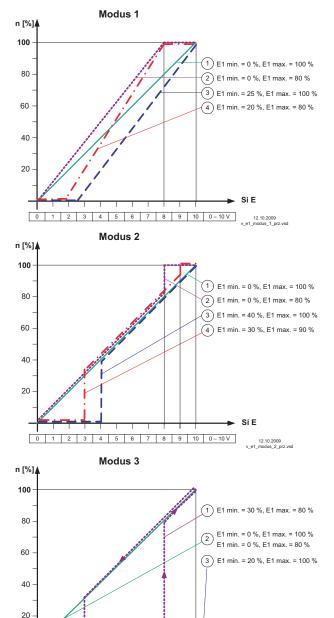
Setting options depending on the version of the software available! These settings are mostly practical for the operating mode with rotational speed specification over an external signal. In operating modes (as of 2.01) this setting is not suited for influencing the regulation process.

IO Setup	
0 E1 Modus	<ul> <li>E1 Modus</li> <li>[0] = E1 min. / E1 max. without function (factory setting)</li> <li>[1] = Offset / turn</li> <li>[2] = signal range</li> <li>[3] = Hysteresis setting On / Off (function depending on the version of the software available)</li> </ul>
IO Setup	
	E1 Min.
0 %	Setting range: 0 - 100 %
E1 Min.	Factory setting: 0 %
IO Setup	
	E1 max
0 %	Setting range: 0 - 100 %
E1 max	Factory setting: 100 %
IO Setup	



0 E2 Mode	<ul> <li>E2 Mode</li> <li>0 = E2 min. / E2 max. without function (factory setting)</li> <li>1 = Offset / turn</li> <li>2 = signal range</li> </ul>
IO Setup	
	E2 min.
0 %	Setting range: 0 - 100 %
E2 min.	Factory setting: 0 %
IO Setup	
	E2 max.
0 %	Setting range: 0 - 100 %
E2 max.	Factory setting: 100 %





#### Example for Mode "1.01" with speed setting signal 0 - 10 V

#### Modus 1

Example: "E1 min." = 20 % The controller begins only at approx. 20% higher signal with minimal modulation.

Example: "E1 max." = 80 % The modulation rises linear to 100% modulation with 80% setting signal.

#### Modus 2

Example: "E1 min." = 30 % Only with approx. 30 % setting signal the controller begins with approx. 30% modulation.

Example: "E1 max." = 80 % Over 80 % setting signal the modulation is switched to 100 % modulation.

#### Modus 3

Example: "E1 min." = 30 %, "E1 max." = 80 % Over approx. 80 % setting signal the modulation is switched on. Below approx. 30 % setting signal the modulation is switched off.

For a correct function: E1 min. higher 0 % and E1 max. below 100 %. example 2 and 3 only for information.

Idealized principle diagrams for setting: "Min. Speed" = 0 % and "Max. Speed" = 100 %

2 3 4 5 6 7 8 9 10 0-10V



0



Si E

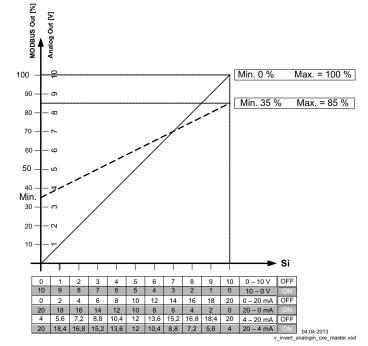
12.10.2009 v\_e1\_modus\_3\_prz.vsd

#### 9.5.3.2 Inverting analog inputs "E1" / "E2"

After programming the signal or sensor type, an inversion of the inputs can be carried out.

IO Setup	Factory setting for Inverting inputs = "OFF" (if input activated) (signal: 0 - 10 V, 0 - 20 mA, 4 - 20 mA).
OFF E1 Inverting	For activation using inverted default signals or sensors with inverted output signals proportional to the measurement range, switch inverting to "ON" (Signal: 10 - 0 V, 20 - 0 mA, 20 - 4 mA).
IO Setup	
OFF E2 Inverting	

Example: mode **1.01** speed controller, setting by external signal



MODBUS Out: speed setting over MODBUS Analog Out: speed setting over analog output 0 - 10 V Si Signal OFF Inverting = OFF ON Inverting = ON

#### 9.5.3.3 "E1" / "E2" Bus mode

After programming the signal or sensor type, the raw value (0-32767) of an analog sensor input can be written in a Holding Register (h9000 for E1 and h9001 for E2) with the bus mode activated. The connection is made at the MODBUS RTU Slave interface. Connecting terminals: 2A (2D+), 2B (2D-).

IO Setup	The bus mode of the inputs is set to "OFF" at the factory.
OFF	With activated bus mode, the raw values can be written accordingly into the Holding Registers, addresses h9000 and h9001 for "E1" and "E2".
E1 Busmode	
IO Setup	
OFF E2 Busmode	



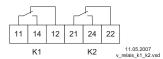
# 9.5.4 Function and inverting for relay outputs "K1" and "K2"

IO Setup	Various functions can be allocated to the relay outputs "K1" and "K2". In case of the			
Operating indication (1K) K1 Function	same function allocation for "K1" and "K2", these work parallel. The inversion of the relays "K1" and "K2" is set at the factory to "OFF" (when a function is programmed). For switching inversion to "ON" (switching behaviour dependent on assigned function)			
IO Setup	The relays can only pull up basically when the voltage supply of the electronics is working. Three-phase current devices must have at least 2 line phases!			
OFF K1 Inverting				
IO Setup				
Fault indication (2K) K2 Function				
IO Setup				
OFF K2 Inverting				

Function	Description		
	no function		
OFF	Relays remain always de-energized.		
Operating indication	Operating indication (factory setting for "K1", non inverting).		
(1K)	Operation without fault, reports enable "OFF"		
Fault indication	Fault indication (factory setting for "K2", non inverting).		
(2K)	Pulled up in operation without fault, with release "OFF" not dropped out.		
	Drops out in case of line and device fault and external fault at the digital input. Depend- ing on programming in event of sensor failure.		
	When networked via the MODBUS Master interface, fault indication in case of faulty MODBUS connection and fault on a member.		
External error (3K)	External fault separate with message at digital input (factory setting if terminals bridged).		
Limit modulation	Limit modulation		
(4K)	Over or falling below limits for modulation.		
Limit E1	Limit "E1"		
(5K)	Whenover or falling below limits for input signal "E1".		
Limit E2	Limit "E2"		
(6K)	Whenover or falling below limits for input signal "E2".		
	For modes as controller (from 2.01.)		
Setpoint Offset	Limit: Setpoint offset (only for active Setpoint control circuit 1).		
(7K)	Deviation between actual value and setpoint to high.		
Group2	Group control (Group 2)		
(8K)	Switching on fans depending on modulation		
Group3	Group control (Group 3)		
(12K)	Switching on fans depending on modulation		
Group4	Group control (Group 4)		
(14K)	Switching on fans depending on modulation		
	For modes as temperature controller with additional functions 2.03		
2.Heating	Heating function		
(9K)	Switch ON point: temperature = Setpoint +/- Offset		
	Switch OFF point: Temperature around hysteresis over switch ON point		
2.Cooling	Cooling function		
(10K)	Switch ON point: temperature = Setpoint +/- Offset		
	Switch OFF point: Temperature around hysteresis below switch ON point		







- K1 1 = energized, terminals 11-14 bridged 0 = de-energized, terminals 11-12 bridged
   K2 1 = energized, terminals 21-24 bridged 0 = de-energized, terminals 21-22 bridged

Function	on Controller status K1		K2	
		1 = ene	1 = energized	
		0 = de-ei	nergized	
		Inve	rting	
		OFF	ON	
1K	Operation without fault, line supply okay	1	0	
2K	Fault with indication by relay	0	1	
3K	External Fault at digital input for external fault		0	
4K	4K Over or falling below modulation		0	
5K	5K over or falling below limits for input signal "E1"		0	
6K	over or falling below limits for input signal "E2"	1	0	
7K	setpoint deviation to high	1	0	

#### 9.5.5 COM2 Function

IO Setup	Possible settings:
MODBUS Slave COM2 Function	<ul> <li>MODBUS Slave (factory setting): In the main menu the "Diagnostic" menu group is followed by the "MODBUS Slave" menu group. The communication parameters can be set in this.</li> <li>OFF: The "MODBUS Slave" or "MODEM SMS" menu group is not displayed in the main menu.</li> <li>MODEM SMS: In the main menu the "IO Setup" menu group is followed by the "MODEM SMS" menu group. Input SIM PIN for MODEM SMS interface (no function at present).</li> </ul>



#### 9.6 Limits

#### 9.6.1 Limit indication depending on modulation

only for Modulation control circuit 1!

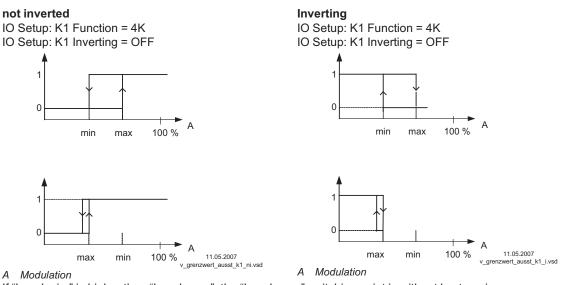
Display for operation with two control circuits: 1.Modul. function, 1.Modulation min., 1.Modulation max., 1.Modul. Delay

Limit	Following functions can be allocated to the limit indication			
OFF Controller function	OFF	no function (factory setting)		
	Fault (1L)	Limit alarm alternating with actual value display Is listed in the protocol as an alarm. Indication with the centralized fault of a programmed relay (IO allocation Function $2K$ ).		
	Message (2L) Is listed in the protocol as a message. There is no alternating message on the actual value display and no message via alarm relay.			
	Filter error (3L) Like function 1L with fault message "Filter"			
	Filter Message (4L)	Like function 2L with fault message "Filter"		
	In the IO setup, a separate relay can be allocated independent of these settings.			
Limit	If the modulation e "Level min" has be	exceeds the set "Level max" value, this is reported until the set value een undercut.		
30 % Level min.	The indication is delayed by the time set in "Display delay". Setting range: 0 - 100 % Factory setting: 30 % / 40 % *			
Limit	-			
40 % Level max.	-			
Limit	Time delay exceed Setting range: 0 -	ding "Level max." up to indication by relay and alarm symbol. 120 sec.		
2 sec Level Delay	Factory setting: 2			

\* Display ---- as long as function = OFF



#### Example indication by relay "K1":



If "Level min." is higher than "Level max.", the "Level max." switching point is without hysteresi.

#### 9.6.2 Limit indication depending on setting or sensor signal

Same procedure for analogue	inputs "E1" and "E2".
-----------------------------	-----------------------

Limit	Following functions can be allocated to the limit indication		
OFF Lmt E1 Function	OFF	no function (factory setting)	
	Fault (1L)	Limit alarm alternating with actual value display Is listed in the proto- col as an alarm. Indication with the centralized fault of a programmed relay (IO alloca- tion Function [2K]).	
	Message (2L)	Is listed in the protocol as a message. There is no alternating mes- sage on the actual value display and no message via alarm relay.	
	Filter error (3L)	Like function 1L with fault message "Filter"	
	Filter Message (4L)	Like function 2L with fault message "Filter"	
	In the IO setup, a separate relay can be allocated independent of these settings.		
Limit  Lmt E1 min	act on a relay tog relay is allocated, Work can be carr The same setting	1 ("E1 min" and "E1 max") can be set independent of each other and ether if correspondingly programmed. If a function is activated or if a both settings ("min" and "max") are initially at "OFF". ied out with one as well as with both limit indicators. applies to "E2 Min." and "E2 Max.", described below for "E1".	
Limit	Undercutting the signal ("E1 min"). If the signal undercuts the set value "E1 min", this is reported until the set value (plus adjustable hysteresis) has been exceeded once again.		
	Exceeding the signal ("E1 max").		
Lmt E1 max.	If the signal exceeds the set value "E1 max", this is reported until the set value (minus hysteresis) has been undercut once again.		
Limit	<b>E1 Hysteresis</b> Hysteresis adjust	ment in the unit of measure of the programmed input signal.	
Lmt E1 Hyst.	-		



Limit	E1 Delay		
	Time delay exceeding "Level max." up to indication by relay and alarm symbol.		
	Setting range: 0 - 120 sec.		
Lmt E1Del.	Factory setting: 2 sec.		

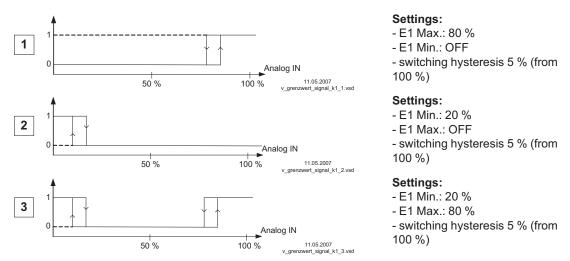


#### Information

Always adjust the value for the maximum input signal higher than the value for the minimum input signal!

E1 Max. > E1 Min.

#### Example for a limit indication of default signal or sensor signal to "Analog In 1"



Terminal "E1" and "GND" alarm via relay "K1" (non-inverted) IO Setup  $\rightarrow$  K1 function: [5 K] = limit indicators

#### 9.6.3 Limit indication depending on (offset) to Setpoint

In operating modes as a controller (starting from **2.01**), two limit indicators can be carried out based on the set target value (Setpoint) and measured actual value (on E1).

Only for active Setpoint of control circuit 1!

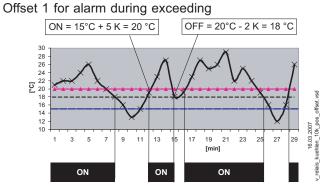
Display for operation with two control circuits: 1.Offset function, 1.Offset 1, 1.Offset 2, 1.Offset hyst., 1.Offset Delay

Limit	Following functions can be allocated to the limit indication. Identical setting for both analogue inputs "E1" and "E2".		
OFF Offset Function	OFF	no function (factory setting)	
	Fault (1L)	Limit alarm alternating with actual value display Is listed in the proto- col as an alarm. Indication with the centralized fault of a programmed relay (IO alloca- tion Function $\boxed{2K}$ ).	
	Message (2L)	Is listed in the protocol as a message. There is no alternating mes- sage on the actual value display and no message via alarm relay.	
	Filter error (3L)	Like function 1L with fault message "Filter"	
	Filter Message (4L)	Like function 2L with fault message "Filter"	
	In the IO setup, a separate relay can be allocated independent of these settings.		



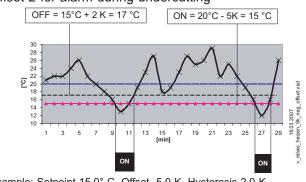
Offset 1, Offset 2	
Both values for Offset 1 and Offset 2 can be set independent of each other and act on a relay together if correspondingly programmed. If a function is activated or if a relay is allocated both settings (Offset 1 and Offset 2) are initially at "OFF". Work can be carried out with one as well as with both limit indicators.	
"Offset 1" for alarm in case of an exceeding of the max. deviation between actual and target.	
Switch ON point: actual value = Setpoint +/- offset	
Swtich OFF point: Actual value by hysteresis under the switch-on point	
"Offset 2" for alarm in case of an undercutting of the max. deviation between actual and target	
Switch ON point: actual value = Setpoint +/- offset	
Swtich OFF point: Actual value by hysteresis over the switch-on point	
Offset Hysteresis	
Hysteresis switch-on point: In temperature regulation + / - 10 K, otherwise sensors 10 % of measurement range	
Offset Delay	
Time delay until indication through relay and alarm symbol.	
Setting range: 0 - 120 sec.	
Factory setting: 2 sec.	

Example for temperature regulation; for other modes of operation settings in corresponding sensor unit.



Example: Setpoint 15.0 °C, Offset +5.0 K, Hysteresis 2.0 K

#### Offset 2 for alarm during undercutting



Example: Setpoint 15.0° C, Offset -5.0 K, Hysteresis 2.0 K



#### 9.7 Timer

#### 9.7.1 Timerfunction

The device has a real time clock. The clock is backed up (Gold Cap) and has a reserve of 2 or 3 days after sufficient operation on a voltage supply.

The time and date must be set during start-up operation and when using the real-time clock. The device calculates the weekday based on the date.

In principle, the timer function acts like a digital switch input (timer "On"  $\triangleq$  closed contact at inverting OFF). The same functions can be assigned to the timer switch as the digital inputs("D1 ..D2)".

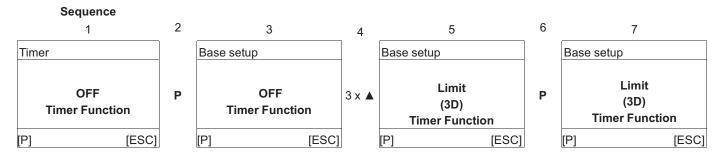
Function	Description *	Timer ON =	
	2000.1910.0	(@ Timer Invert. = OFF)	
OFF	no function (factory setting)		
Enable	Enable (remote control) "ON" / "OFF"		
(1D)		Device ON	
External error	External fault alarm	Foult	
(2D)		Fault	
Limit	"Limit" ON / OFF		
(3D)	Influences control circuit 1 and control circuit 2 in operation with two control circuits	Limit ON	
E1 / E2	Switch over input "E1" / "E2" (for operation with one control	Signal at E2	
(4D)	circuit)		
Reset (10D)	Complete re-start of the device	Reset	
Max. Speed	Setting Max. Speed "ON" / "OFF"		
(11D)	Influences the respectively set value "1. Max. Speed" and "2. Max. Spe Max. Speed" in operation with two control circuits.		
Override Time	Do not use function for timer (only for digital input).		
(21D)		-	
For mode speed controller 1.01			
Setpoint1/2	Switch over "Set Intern1" / "Set Intern2"		
(5D)	"Setting External 1" must be at "OFF".	Set Intern2	
Setpoint int./ext.	Switch over "Intern" / "Extern"	Set extern	
(6D)			
	For modes as controller (from 2.01.)		
Setpoint1/2	Switch over "Setpoint 1" / "Setpoint 2"for control circuit1		
(5D)		Setpoint2	
Setpoint int./ext.	Switch over "Intern" / "Extern"	Cotraint External	
(6D)	Possible only for operation with one control circuit!	Setpoint External	
Control/Manual	Switch over "automatic control" / "Speed manual"	Manual mode	
(7D)	Possible only for operation with one control circuit!		
Heating/Cooling (8D)	Switch over control function (e.g. "heating" / "cooling")	Reversal standard	
1.Setp+Pband1/2	for control circuit 1: Switch over Setpoint 1/2 and Pband 1/1	First control circuit Set-	
(15D)	When programming this function, "Setting" additionally lists the parameter: "1.Pband2 for control circuit 1."	point 2 + Pband 2	
	Only active in operation with a second control circuit		
E1 / E2 (4D)	The output for control circuit 2 is additionally set to "A2" to "A1" (regardless of the programmed function for "A1"). The first control circuit has no output for the duration of the switch over. The switch over input "E1" / "E2" as in operation with one control circuit is no longer possible.	Second control circuit to A1 + A2	



Function	Description *	Timer ON =
		(@ Timer Invert. = OFF)
		Ċ
2. Setpoint 1/2	for control circuit 2: Switch over "2. Setpoint 1" / "2. Setpoint	Second control circuit
(9D)	2"	Setpoint 2
2.Setp+Pband1/2	for control circuit 2: Switch over Setpoint 1/2 and Pband 1/2	
(16D)	When programming this function, "Setting" additionally lists the parameter: "2Pband2 for control circuit 2."	Second control circuit Setpoint 2 + Pband 2

\* Detailed description @ IO Setup / Digital Inputs "D1" / "D2"

#### Example: Programming limitation for output voltage (Limit ON / OFF)



#### 9.7.2 Setting of time and date

Main menu	Menu group timer
Controller Setup	
IO Setup	
Limit	
Timer	
Automatic addressing	_
Timer	Press the P-key and set the hours with the UP / DOWN keys, press the P-key to save.
	Now the minutes flash and can be set with the UP / DOWN keys, press the <b>P-key</b> to
13:05	save.
Time	
Timer	To set the date follow the same method as for "Time". The date setting consists of day, month and year
09.04.13	Example for: 9. April 2013
Date	

#### 9.7.3 Automatic summer time

The summertime automatic is factory set to "OFF", i.e. switched off. When the summertime automatic is activated the device automatically switches between daylight saving time and wintertime. "North" = for countries in the Northern Hemisphere.

"South" = for countries in the Southern Hemisphere.

		for Northern Hemi- sphere	for Southern Hemi- sphere
Timer	$\rightarrow$	Timer	Timer



OFF	North		South	
Summertime Auto.	Summertime Auto.		Summertime Auto.	
		-		



#### Information

If the summer time automatic is used, the switch over date and the switch over time are identical and unchangeable for both settings.

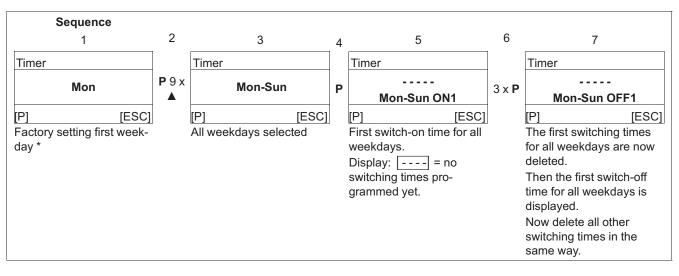
The time is put forward from 2:00 am to 3:00 am respectively on the last Sunday in March (South put back from 3:00 am to 2:00 am) and put back from 3:00 am to 2:00 am (South put forward from 2:00 am to 3:00 am) on the last Sunday in October.

If other dates for the switch over between summer time and winter time are required, the clock must be changed by hand (manually) on the respective date.

#### 9.7.4 Enter switching times

**Two** switching times can be entered for the same function (e.g.  $\exists D = Limit$ ) for each weekday. The menu items are repeated for each weekday with two on- and off-times each. Switching times are not preprogrammed at the factory.

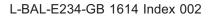
In order to make configuration easier, the same switching times can be made for several days in a block. To prevent unwanted switching times from arising, all should be deleted before programming. To do this, select the block Mo - Su and deactivate all 4 switching times.



#### Be sure to delete all switching times before carrying out complete new settings.

\* If switching times are already programmed for all weekdays "Mon-Sun", press the P key and increase the hours with the ▲key until the deactivation appears after "23", display: \_---. Then press the P key twice to confirm and delete the switching times.

All programmed switching times are deleted after loading the factory setting or resetting the mode.





	Mon-Sun													
Mon-Fri											Sat-Sun			
Mon Tue				Wed		Thr		Fri		Sat		Sun		
ON1	:	ON1	:	ON1	:	ON1	:	ON1	:	ON1	:	ON1	:	
OFF1	:	OFF1	:	OFF1	:	OFF1	:	OFF1	:	OFF1	:	OFF1	:	
ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	
OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	

Example	e 1: Ever	y day at a	8 am ON	and at 6	pm OFF								
						Mon	-Sun						
		[	[	[	[	ſ	[	ſ	[		ſ	[	r
ON1	08:00	ON1	08:00	ON1	08:00	ON1	08:00	ON1	08:00	ON1	08:00	ON1	08:00
OFF1	18:00	OFF1	18:00	OFF1	18:00	OFF1	18:00	OFF1	18:00	OFF1	18:00	OFF1	18:00
ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	ON2	:
OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:

	Mon-Fri											Sat-Sun			
ON1	06:00	ON1	06:00	ON1	06:00	ON1	06:00	ON1	06:00	ON1	:	ON1	:		
OFF1	08:00	OFF1	08:00	OFF1	08:00	OFF1	08:00	OFF1	08:00	OFF1	:	OFF1	:		
ON2	17:00	ON2	17:00	ON2	17:00	ON2	17:00	ON2	17:00	ON2	:	ON2	:		
OFF2	22:00	OFF2	22:00	OFF2	22:00	OFF2	22:00	OFF2	22:00	OFF2	:	OFF2	:		

M	on	Τι	le	W	ed	Т	hr	F	ri	S	at	Si	un
		·											
ON1	:	ON1	:	ON1	18:00	ON1	:	ON1	:	ON1	:	ON1	:
OFF1	:	OFF1	:	OFF1	:	OFF1	08:00	OFF1	:	OFF1	:	OFF1	:
ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	ON2	:	ON2	:
OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:	OFF2	:

Free tables for entering individual timer settings	
--	--

M	on	Tu	е	We	ed	Tł	۱r	F	ri	S	at	Su	ın
ON1		ON1		ON1		ON1		ON1		ON1		ON1	
OFF1		OFF1		OFF1		OFF1		OFF1		OFF1		OFF1	
ON2		ON2		ON2		ON2		ON2		ON2		ON2	
OFF2		OFF2		OFF2		OFF2		OFF2		OFF2		OFF2	



#### 9.7.5 Inverting timer function

Inverting of the timer function is possible if required.

Timer	Timer Inverting
OFF Timer Inverting	In the "OFF" setting (factory setting), the programmed function is activated at the switch-on time (clock icon in the display) and deactivated again at the switch-off time ( I time function).
Timer inverting	In the "ON" setting, the programmed function is deactivated at the switch-on time and activated again at the switch-off time (clock icon in the display).

#### 9.7.6 Overwrite timer function

The timer output can be overwritten for a settable time with a selectable status if required. Activation is by a digital input ( $\Im$  IO Setup function 21D)

Application: Exceptions from the normal timing operation, e.g. for manual or automatic presence switch, party mode, etc.

Timer	Override Time
120 min Override Time	Settable time for overwriting the timer function Setting range: 065535 min. Factory setting: 120 min
	In the "0 min." setting, the timer function is overwritten with the selected status until the next timing change.
Timer	Override Status
OFF Override Status	Settable status when overwriting the timer function: ON = function as for timer ON @ timer function OFF = function as for timer OFF (factory setting)

#### 9.7.7 Adjustment of the real time clock

Timer	Fine adjustment of the real time clock is possible if required.
00	The greater the value, the slower the clock runs. If the value is increased by one point, this corresponds to a slowing of the clock by approx. 2 to 3 s per month. Setting range: 0 - 127 Factory setting: 60

#### 9.8 MODBUS Slave

Addressing and configuration of the MODBUS Slave interface.

Via this interface the device can be networked with a master building control system, the device then operates as a pure Slave and uses the MODBUS-RTU protocol.

The connection is made to the terminals "2A (2D+)", "2B (2D-)" of the MODBUS Slave interface ( Installation / RS-485 interfaces for MODBUS RTU).



#### Information

- In the IO Setup the "COM function must be set" to "MODBUS Slave" so that this menu group is displayed (factory setting).
- MODBUS settings (baud rate, parity) are saved after a reset ( menu group "Start" -> "Reset" or interrupt voltage supply).



MODBUS Slave	Bus Address The device address is factory set to the highest available MODBUS address: 247.
247 Bus Address	Setting range MODBUS Address: 1 - 247.
Bus Audress	_
MODBUS Slave	Addressing
	Switch addressing to "ON" before setting "address".
OFF	
Addressing	
MODBUS Slave	UART Baudrate
	Setting transfer rate
19200	Valid values: 4800, 9600, 19200, 38400, 115200 Factory setting: 19200
UART Baudrate	
MODBUS Slave	UART Mode
	Setting transfer format
8E1	Valid values: 8O1, 8N1, 8E1
UART Mode	Factory setting: 8E1

#### 9.9 MODBUS Master

Addressing of the members that are activated via the MODBUS Master interface. Addressing can be done automatically by a patented method. It is then no longer necessary to address every single member manually in the network.

Alternatively, manual addressing is possible, for which separate components are required for setting the individual member address.



#### Information

- A maximum of 32 devices can be connected. The communication settings are pre-set to 19.2kbd, 8E1 and cannot be changed.
- To ensure activation, the function of the digital input "D1" of the members is automatically set to "OFF" by the MODBUS Master. I.e. any programmed enable function for switching off the member (by a potential-free contact) is no longer active.

Main menu		MODBUS Master
MODBUS Maste	r	After addressing (manual or automatic), the devices are subsequently listed to the
Fan 1 (2A)		"MODBUS Master" menu group (@"members MODBUS Master").
Fan 2 (2A)		
Fan 3 (2A)		
[P] Enter	[ESC] Info	





#### 9.9.1 Automatic addressing

- The first member (MODBUS address 1) must be connected to the terminals 1A(1D+) and 1B (1D-), additionally the "ID" connections must be connected ( ID" installation / communication / addressing members MODBUS Master interface).
- The members are automatically addressed consecutively according to the installation.
- In order to do the automatic addressing successfully, all the bus members to be addressed must be connected with each other, applied to voltage and switched on.

The automatic addressing can only be done with compatible devices!

Main menu	MODBUS Master
Limit	
Timer	
Diagnostic	
MODBUS Master	
[P] Enter [ESC] Info	
MODBUS Master	1. <b>Press the P-key</b> to open the "MODBUS Master".
	2. Press the P-key to select automatic addressing.
Autoaddressing	3. <b>Press the P-key</b> to start automatic addressing.
[P] Enter [ESC] Menu	
MODBUS Master	Display while the automatic addressing is in progress.
Addressing	
Found: 0	
In progress	
[P] Repeat [ESC] Cancel	
MODBUS Master	The found members count is displayed at the end of automatic addressing.
Addressing	Press the <b>P-key</b> again to repeat the addressing.
Found: 5	Exit the menu with the Esc key combination $ abla + \Delta$ .
Done	
[P] Repeat [ESC] Cancel	

#### 9.9.2 Manual addressing

The addressing is done manually by a separate hand held terminal or PC software, the corresponding member count must be entered on the MODBUS Master.

- The members are connected to the device by the terminals 1A(1D+) and 1B (1D-) (relation / communication).
- All bus members must be addressed uniquely, consecutively and starting at address **1**. Otherwise communication could be disturbed or no communication can be set up.
- In order to complete the manual addressing successfully, all the bus members to be addressed must be connected with each other, applied to voltage and switched on.

Main menu		MODBUS Master
Limit		
Timer		
Diagnostic		
MODBUS Master		
[P] Enter	[ESC] Info	
MODBUS Master		Press the P-key to open the "MODBUS Master".
Autoaddres	sing	
[P] Enter [I	ESC] Menu	
MODBUS Master		Press the ▼ -key to select the "Bus Slavecount" menu.
0		
Bus Slavec	ount	





[P] Edit [ESC] Menu		
MODBUS Master		Press the P-key to open the menu.
		Set the correct member count with the $\mathbf{\nabla} \mathbf{A}$ keys and confirm with the <b>P-key</b> .
5		Exit the menu with the Esc key combination $ abla$ + $igashiftsimeq$ .
Bus Sla	avecount	
[P] Edit	[ESC] Menu	

Info	Error message when entering too high a member count, alternately with the actual
Error MODBUS Com Fan: 2	value display.

# 9.10 Member MOBUS Master

After addressing, (manual or automatic) the members are then listed to the "MODBUS Master" menu group.

Main menu		The function for activation by MODBUS is displayed after the address of the
MODBUS Master		member.
Fan 1 (2A)		The same function is programmed initially for all members after addressing. 1.
Fan 2 (2A)		Control Signal (2A).
Fan 3 (2A)		I.e. every member is activated by the output of control circuit 1.
[P] Enter	[ESC] Info	

After selection with the  $\checkmark$   $\blacktriangle$  keys, press the **P-key** to open the State menu of the member (menu content depends on the type of member).

#### State menu member Example: ECblue fan

Fan 1 (2A)	
ECblue V13.05	← Device type and firmware version
Fan OK!	← Operating state of the member
Speed [rpm 570]	← Speed Actual value (1/min)
Motorcurrent [A] 2.60	← Current consumption
P=0W Level=0%	← Power consumption and modulation of the device
[P] Edit [ESC] Menu	

To set the MODBUS function for the member, press the **P-key**.

Fan 1 (2A)	Press the P-key to open the menu.
1st control signal	Select the desired MODBUS function with the $\blacksquare$ keys and save with the <b>P-key</b> .
(2A)	Pre-programmed function 1. Control Signal (2A) = output of control circuit 1.
MB Function	For example, to activate speed controllers for fans or fans with integrated con- troller and MODBUS interface.
[P] Edit [ESC] Menu	The programmable functions correspond to the functions for the analogue outputs (@ IO Setup).
	<ul> <li>For members activated by control circuit 2, function: [2. Control Signal (8A)]</li> <li>For members activated in groups (function: [5A], [11A], [12A]), the "Group Version" setting must be observed, at factory setting "OFF" there is no activation (@ Controller Setup)!</li> </ul>

Exit the menu with the Esc key combination  $\nabla + \blacktriangle$ .



# 10 Menu tables

# 10.1 Menues of operating modes

Mode	4.01	4.02	User Setting
Parameter	Factory	setting	
	Info		
E1 Actual	88.7 Pa	88.7 Pa	
E2 Actual		21.0 °C	
Setpoint1	250.0 Pa	250.0 Pa	
1.Setpoint 1 <sup>2</sup>			
2.Setpoint 1 <sup>3</sup>			
Setpoint control		100 Pa	
Modulation	0 %	0 %	
1. Control <sup>2</sup>			
1. Control <sup>3</sup>			
Min. speed cut off 1. Min. speed cut off <sup>2</sup>	OFF	OFF	
2. Min. speed cut off <sup>3</sup>			
	Start		
PIN input			
Language	GB	GB	
US units	OFF	OFF	
Reset	OFF	OFF	
Mode	4.01	4.02	
XXX	11.16	11.16	
SN:	000005E45536	000005E45536	
		00000240000	
	Setting		
Setpoint1	050 0 Da	250 0 De	
1.Setpoint 1 <sup>2</sup>	250.0 Pa	250.0 Pa	
Setpoint2	250.0 Pa	250.0 Pa	
1.Setpoint 2 <sup>2</sup>	230.0 Fa	230.0 Fa	
Pband	250.0 Pa	250.0 Pa	
1. Pband 1 <sup>2</sup>			
1. Pband 2 <sup>4</sup>			
Min. Speed	0%	0%	
1.Min. Speed <sup>2</sup>			
Max. Speed 1. Max. Speed <sup>2</sup>	100 %	100 %	
2.Setpoint 1 <sup>3</sup>			
2.Setpoint 2 <sup>3</sup>			
2. Pband 1 <sup>3</sup>			
2. Pband 1 <sup>5</sup> 2. Pband 2 <sup>5</sup>			
2. Min. Speed <sup>3</sup>			
2. Max. Speed <sup>3</sup>			
Z. Max. Speed Manual mode			
1. Manual mode <sup>2</sup>	OFF	OFF	
Speed manual			
1. Speed man. <sup>2</sup>	100 %	100 %	
T-Band SA		30.0 K	
T-Start SA		15.0 °C	
Min. Setpoint		70 Pa	

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4.01	4.02	User Setting
Factory	setting	
Protocol		
	4.00	
	149.9 °C	
Controller Setu	qu	
OFF	OFF	
OFF	OFF	
OFF	OFF	
ON	ON	
055	055	
OFF	OFF	
OFF	OFF	
Pid	Pid	
0 %	0 %	
0	0	
	Factory           Frotocol           Protocol           Ease setup           E.O1           INT500           INT500	Factory setting         Image: Setting           Protocol         Image: Setup           Base setup         Second setup           Ease setup         Second setup           Ease setup         Second setup           Image: Second setup         Image: Second setup           Image: Second setup <thimage: second="" setup<="" th="">         Image: Second</thimage:>

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Mode	4.01	4.02	User Setting	
Parameter		setting		
External message		External error		
Offset control sig. 1	0 %	0 %		
Selection amplifier	OFF	OFF		
	IO Setup			
A1 Function	2A	2A		
A1 min.	0.0 V	0.0 V		
A1 max.	10.0 V	10.0 V		
A1 Inverting	OFF	OFF		
A2 Function	1A	1A		
A2 min.	0.0 V	0.0 V		
A2 max.	10.0 V	10.0 V		
A2 Inverting	OFF	OFF		
D1 Function	5D	5D		
D1 Inverting	OFF	OFF		
D1 Busmode	OFF	OFF		
D2 Function	OFF	OFF		
D2 Inverting				
D2 Busmode				
D - D Relation	OG	OG		
E1 Inverting	OFF	OFF		
E1 Busmode	OFF	OFF		
E2 Inverting		OFF		
E2 Busmode	OFF	OFF		
K1 Function	1K	1K		
K1 Inverting	OFF	OFF		
K2 Function	2K	2K		
K2 Inverting	OFF	OFF		
COM2 Function		JS Slave		
	Limit			
Level Function 1. Level. Function <sup>2</sup>	OFF	OFF		
Ausst. min. 1.Ausst. min. <sup>2</sup>				
Level max. 1. Level max. <sup>2</sup>				
Level Delay 1. Level Delay <sup>2</sup>				
Lmt E1 Function	OFF	OFF		
GW E1 min.				
Lmt E1 max.				
Lmt E1 Hyst.				
Lmt E1 Del.				
Lmt E2 Function		OFF		
GW E2 min.				
Lmt E2 max.				
Lmt E2 Hyst.				
Lmt E2 Del.				
Offset Function	OFF	OFF		
1. Offset Function <sup>2</sup>	UFF	UFF		



Mode	4.01	4.02	User Setting
Parameter	Factory	v setting	
Offset 1		0	
1.Offset 1 <sup>2</sup>			
Offset 2			
1.Offset 2 <sup>2</sup>			
Offset Hyst.			
1. Offset Hyst. <sup>2</sup>			
Offset Delay			
1. Offset Del. <sup>2</sup>			
Time	Timer		
Date	14:24	14:24	
Summertime Auto.	19.04.13	19.04.13	
Timer Function	OFF	OFF	
Mon	OFF	OFF	
Mon ON1			
Mon OFF1	:	:	
Mon ON2	:	:	
Mon OFF2	:	:	
Timer Inverting	:	:	
Override Time	OFF	OFF	
Override Status	120 min	120 min	
	OFF	OFF	
RTC Adjust	60	60	
	Diagnostic		
Runtime Controller	000056:46:13	000056:46:13	
Runtime Motor	000056:46:13	000056:46:13	
E1 - KTY	20.0 °C	20.0 °C	
E1-Current	0.00 mA	0.00 mA	
E1 - Voltage E2 - KTY	0.00 V	0.00 V	
	20.0 °C 0.00 mA	20.0 °C	
E2-Current	0.00 MA	0.00 mA 0.00 V	
E2 - Voltage	0.00 V		
D1		OFF	
D2	OFF	OFF	
K1	OFF	OFF	
К2	ON	ON	
	MODBUS Sla	Ve	
Bus Address	247	247	
Addressing	OFF	OFF	
UART Baudrate	19200	19200	
UART Mode	8E1	8E1	
	MODBUS Mas	ster	
Autoaddressing			
Bus Slavecount	0	0	
	v	5	

1 For adjustment "Setting Sep" > 0 (@ Base setup)

2 For control circuit 1 in operation with a second control circuit (@ Base Setup / Function E2)
3 For control circuit 2 in operation with a second control circuit (presetting depending on programmed function)

4 In operation with control circuit 2 and programmed function 15 D for digital input (@ IO Setup)

5 In operation with control circuit 2 and programmed function 16 D for digital input (@ IO Setup)



# 10.2 Possible allocation of the IOs, PINs

#### Units for analog inputs E1 and E2

The following units can be set for programmed sensors with free measuring range (0 - 10 V, 0 - 20 mA, 4 - 20 mA).	
E1 Analog In E2 Analog In	°C, m³/h, bar, %, Pa, m/s, m³/s, Ohm, mbr, °F, ft/s, cfm, in.wg, psi, ppm

#### Analog outputs A1 and A2

Function	Description
OFF	no function
Constant voltage 10 V	Constant voltage +10 V
(1A)	Factory setting for "A2" at operation with one control circuit.
1st control signal	Controlled 0 - 10 V output for control circuit 1 (factory setting for "A1")
(2A)	
E1	proportional input "E1"
(3A)	
E2	proportional input "E2"
(4A)	
Group2	Group control ( C Controller Setup - group 2)
(5A)	
2.Cooling	Only for mode <b>2.03</b> temperature controller with additional functions.
(6A)	Controller output 2 with rising activation at Actual>Nominal = <b>Cool</b> .
2.Heating	Only for mode <b>2.03</b> temperature controller with additional functions.
(7A)	Controller output 2 with rising activation at Actual <nominal =="" heat.<="" th=""></nominal>
2. control signal	Controlled 0 - 10 V output vor control circuit 2.
(8A)	Factory setting for "A2" at operation with second control circuit.
	A second control circuit can be activated if required by programming the E2 function (@ Base Setup E2 functions 8E - 13E and second control circuit)
Speed (9A)	proportionally 1.Control signal
Group1	Group control (@ Controller Setup - group 1)
(10A)	
Group3	Group control (@ Controller Setup - group 3)
(11A)	
Group4	Group control (@ Controller Setup - group 4)
(12A)	

# Digital inputs D1 and D2

Function	Description
OFF	No function (factory setting for D2)
Enable (1D)	Enable (remote control) "ON" / "OFF"
External error (2D)	External fault alarm
Limit (3D)	"Limit" ON / OFF Influences control circuit 1 and control circuit 2
E1 / E2 (4D)	Switch over input "E1" / "E2" (for operation with one control circuit)
Setpoint1/2 (5D)	Switch over "Setpoint 1" / "Setpoint 2" für control circuit 1 (factory Setting for D1)





Setpoint int./ext.	Switch over "Intern" / "Extern"
(6D)	Possible only for operation with one control circuit!
Control/Manual	Switch over "automatic control" / "Speed manual"
(7D)	Possible only for operation with one control circuit!
Heating/Cooling (8D)	Switch over control function (e.g. "heating" / "cooling")
Reset (10D)	Complete re-start of the device
	Setting Max. Speed "ON" / "OFF"
Max. Speed (11D)	Influences the respectively set value "1. Max. Speed" and "2. Max. Speed" in operation with two control circuits.
	for control circuit 1: Switch over Setpoint 1/2 and Pband 1/1
1.Setp+Pband1/2 (15D)	When programming this function, "Setting" additionally lists the parameter: "1.Pband2 for control circuit 1."
Override Time (21D)	Overwrite timer function (in operation with timer)
	Only active in operation with a second control circuit
E1 / E2 (4D)	The output for control circuit 2 is set additionally to "A2" to "A1" (regardless of the programmed function for A1). The first control circuit has no output for the duration of the switch over. The switch over input "E1" / "E2" as in operation with one control circuit is no longer possible.
2. Setpoint 1/2 (9D)	for control circuit 2: Switch over "Setpoint 1" / "Setpoint 2"
2.Setp+Pband1/2 (16D)	for control circuit 2: Switch over Setpoint 1/2 and Pband 1/2 When programming this function, "Setting" additionally lists the parameter: "2Pband2 for control circuit 2."

# Analogue input E2

Function	Description Function E2
OFF	no function (factory setting)
Ext. Manual mode (2E)	External manual operation via external signal (0 - 10 V). Switch over between settings on the device and external manual operation via digital input.
Average E1 (3E)	Sensor average with E1 ( mode 2.04)
Comparison E1 (4E)	Sensor comparison with E1 (@mode 2.04)
Difference E1 (5E)	Sensor difference to E1 (@mode 2.05)
Setpoint derating (6E)	Sensor for setpoint outdoor temperature controlled (@mode 4.02, 5.02).
Measurement (7E)	Measurement value e.g. Measurement value e.g. for limit indication, display in Info menu "E2 Actual".



Function	Description Function E2		
	For activation of a second control circuit		
(only	possible in certain modes ( representation with second control circuit)		
Temperature (8E)	Temperature control, pre-settings and sensor selection correspond to mode 2.01		
Cold-Pressure (9E)	Pressure control condensers, pre-settings and sensor selection correspond to mode <b>3.01</b>		
Cold-Temperature (10E)	Pressure control condensers with input for refrigerant, pre-settings, sensor selection and input for refrigerant corresponding to mode <b>3.02</b>		
Air Pressure (11E)	Pressure control air conditioning, pre-settings and sensor selection correspond to mode <b>4.01</b>		
Air flow (12E)	Volume control, pre-settings, sensor selection and K-factor for inlet ring correspond to mode <b>5.01</b>		
Air speed (13E)	Air velocity control, pre-settings correspond to mode 6.01		

# Digital outputs K1 and K2

Function	Description
OFF	no function
	Relays remain always de-energized
Operating indication	Operating indication (factory setting for "K1", non inverting).
(1K)	Operation without fault, reports enable "OFF"
Fault indication	Fault indication (factory setting for "K2", non inverting).
(2K)	Pulled up in operation without fault, with release "OFF" not dropped out.
	Drops out in case of line and device fault and external fault at the digital input. Depend- ing on programming in event of sensor failure.
External error	External fault separate with message at digital input (factory setting if terminals
(3K)	bridged)
Limit modulation	Limit modulation
(4K)	Over or falling below modulation
Limit E1	Limit "E1"
(5K)	When over or falling below limits for input signal "E1"
Limit E2	Limit "E2"
(6K)	When over or falling below limits for input signal "E2"
Setpoint Offset	Setpoint Offset
(7K)	Deviation between actual value and setpoint to high
Group2	Group control (Group 2)
(8K)	Switching on fans depending on modulation
Group3	Group control (Group 3)
(12K)	Switching on fans depending on modulation
Group4	Group control (Group 4)
(14K)	Switching on fans depending on modulation



#### Limits GW E1 and GW E2

Function	Description function GW E1, GW E2					
OFF	no function					
Fault	Indication with the centralized fault of a programmed relay (IO allocation Function 2K).					
(1L)	Warning symbol in display, "AL" code in events memory.					
Message	Is merely displayed in the events menu as message "msg".					
(2L)						
Filter error	Like function 1L with fault message "Filter"					
(3L)						
Filter Message	Like function 2L with fault message "Filter"					
(4L)						

## PINs

PIN	Function					
PIN 0010	Opening service menu, if PIN-protection activated					
PIN 1234	Opening "setting". if "set protection" = "ON" (@ Controller Setup)					
PIN 9090	Restore user setting					
PIN 9091	Save user setting (corresponds function "Save user setup" = "ON" Controller Setup)					
PIN 9095	Restore factory setting = delivery status					



# 11 Diagnostics menu

Main monu	
Main menu	The diagnostics menu supplies information about the momentary operating condition
IO Setup	of the device.
Limit	
Timer	
Autoaddressing	
Diagnostic	
	-
Diagnostic	Operating hours on the line
	The time counter (h:m:s) runs as soon as line voltage is applied to the device and the
000419:27:28	device is switched on (without failure).
Runtime Controller	If events occur (e.g. sensor failure, MODBUS communication etc.), the operating time
Runtime Controller	at this time is also saved (@ Protocol).
Diagnostic	Operating hours with modulation
	The time counting (h:m:s) runs only when a modulation of the controller is present
000146:23:54	
Runtime Motor	
Diagnostic	Signal height at analog input E1 (Analog In 1)
20.0 °C	
E1 - KTY	
EI-KIT	_
	_
Diagnostic	
9.0 mA	
E1-Current	
Diagnostic	-
	-
4.0 V	
-	
E1 - Voltage	_
Diagnostic	Signal height at analog input E2 (Analog In 2)
20.0 °C	
E2 - KTY	
	-
Diagnostic	-
9.0 mA	
9.0 mA E2-Current	
E2-Current	-
	-
Diagnostic	
4.0 V	
E2 - Voltage	
Diagnostic	Status digital input 1 (Digital In 1)
	ON = terminals D1 - 24V bridged ↔ OFF = terminals D1 - 24V not bridged
OFF	
D1	_



Diagnostic	Status digital input 2 (Digital In 2)
	ON = terminals D2 - 24V bridged ↔ OFF = terminals D2 - 24V not bridged
OFF	
D2	
Diagnostic	OFF = relay K1 de-energized: terminals 11 - 12 bridged
	ON = relay K1 energized: terminals 11 - 14 bridged
ON	
K1	
Diagnostic	OFF = relay K2 de-energized: terminals 21 - 22 bridged
	ON = relay K2 energized: terminals 21 - 24 bridged
OFF	
K2	



## 12 Protocol

## 12.1 Display and query of events and malfunctions

Main menu	Events during operation can lead to a malfunctioning of the device.
Start	The last 100 events are saved in the "Protocol" menu group.
Setting	Position 1 = latest event, display: Protocol 1/100
Protocol	Position 100 = last saved event, display: Protocol 100/100
Base setup	
Controller Setup	The saved events are retained even after resetting to factory setting (@menu group Start / PIN input)!

The device distinguishes between several event types which are identified by different symbols.

## Example

Protocol 1/100	Attention symbol = message		
Modulation	The message is only listed in the protocol. There is no message alternately with the actual value display and no message via alarm relay.		
Runtime Controller	Exception		
000493:04:59	In case of sensor failure there is always a message in the display ( $\ensuremath{\mathfrak{F}}$ Controller Setup / Alarm Sensors) .		
	-		
Protocol 2/100	Bell symbol = Alarm		
Error MODBUS Com Runtime Controller	The alarm message is listed in the protocol and appears alternately with the actual value display.		
000193:04:59	Message by alarm relay depending on the type of failure and programming.		
Protocol 2/100	Cross symbol = previous messages		
Line Fault	Cause of the message no longer exists.		
Runtime Controller			
000493:04:59			

## Example: Previous line failure on a member

Protocol 2/100	
Line Fault	Previous line failure on a member connected via the MODBUS interface.
Runtime Controller 000493:04:59	When the failure was cleared (line voltage available again), the device was on the line for 493 hours, 4 minutes and 59 seconds.
[P] Details [ESC]Me	าน

#### Press the P-key to show further details.

Protocol 2/100	) 🗙	
Line	e Fault	Date and time when the failure was cleared (time setting @ timer)
Date	Time	
15.04.13	10:24	
[P] Details	[ESC]Menu	



Press the P-key to show further details.

Protocol 2/100	X	
Line F	ault	Member on which the failure occurred.
Place		
Fan 1		
[P] Details	[ESC]Menu	

Press the P-key to show further details.

Protocol 2/100	X	
Line Fault Modulation 0 %		Modulation of the member at the time of the message.
[P] Details	[ESC]Menu	

Exit the menu with the Esc key combination  $\nabla + \blacktriangle$ .

## 12.2 Messages and trouble shooting

A momentary pending alarm or error message is indicated by a blinking display and appears alternately with the actual value display.

Display	Relais sv	witches *	Cause	Reaction of Controller
	Opera- tion	Fault		Adjustment
no display	-	_	No line voltage Jumper J1 for USB interface plugged	Line voltage available? Unit switch OFF and automatically ON when the voltage has been re- stored Check line fuse Check jumper J1, pull off or only plug to one PIN
OFF	x	-	No enable	Switch OFF by external contact (function 1D = enable programmed for Digital In)
Factory setting	-	-	fault in Eprom	Works with defaults.
EEP error	-	х	fault EEP damaged	Works with defaults.
EEP Corruption	x	Х	EEP data incorrectly	controller runs with the read settings.
Sensor 1	-	Х	Sensor 1 Interruption / short circuit in the sensor leads or sensor values measured are out- side measuring range	The device works with minimal or maximum modulation depending on whether there is a short-circuit or an interruption, and on the programmed mode of operation. Check sensor
Sensor2	-	х	Sensor2 Interruption / short circuit in the sensor leads or sensor values measured are out- side measuring range	The device works with minimal or maximum modulation depending on whether there is a short-circuit or an interruption, and on the programmed mode of operation. Check sensor



Display	Relais sv	vitches *	Cause	Reaction of Controller
	Opera- tion	Fault		Adjustment
External error * EC Motors Filter Frost protection Adiabatik Firealarm Pressure switch Gas alarm Water alarm RCD	-	Х	Alarm from external contact	Device continues working unchanged. check contacts.
		Moss	ages for programmed limits	
		wess	ayes for programmed limits	•
Modulation Filter **	-	х	Limit alarm modulation	Device continues working unchanged. Content of the second secon
Lmt E1 min Filter **	_	Х	Limit indication minimum Signal actual value at "E1" below setting	Device continues working unchanged. Climit indication depending on set- ting or sensor signal.
Lmt E1 max. Filter **	-	х	Limit indication maximum Signal actual value at "E1" above setting	Device continues working unchanged. Climit indication depending on set- ting or sensor signal.
Lmt E2 min. Filter **	-	х	Limit indication minimum Signal actual value at "E2" above setting	Device continues working unchanged. Climit indication depending on set- ting or sensor signal.
Lmt E2 max. Filter **	-	х	Limit indication maximum Signal actual value above setting	Device continues working unchanged. C Limit indication depending on set- ting or sensor signal.
Offset 1 Filter **	-	х	Limit alarm deviation from Offset 1 too high	Device continues working unchanged. Calculation the deviation from the setpoint.
Offset 2 Filter **	-	х	Limit alarm deviation from Offset 2 too high	Device continues working unchanged. Call Limits depending on the deviation from the setpoint.



Display	Relais switches *		Cause	Reaction of Controller	
	Opera- tion	Fault		Adjustment	
		For o	peration as MODBUS Maste	r	
		6 Master i		nessages of the members are	
Example:					
Error MODBUS Com Fan: 8	-	Х	Connection to the MODBUS Master interface interrupted Entered member count too high	Device continues working unchanged Check member count Check MODBUS connection.	
Motor fault Fan: 3	-	х	Example for motor fault at member with address 3	The control module continues running unchanged. Reset required on the member (@ operating instructions of the device concerned).	
Line Fault Fan: 6	-	Х	Example for line failure at member with address 6	The control module continues running unchanged. Check line supply of member.	

\* Alternative display texts for error message via external contact C Controller Setup / display text for external message.
 \*\* Alternative display texts for limit alarms C limits function 3L



## 13 Enclosure

## 13.1 Technical data

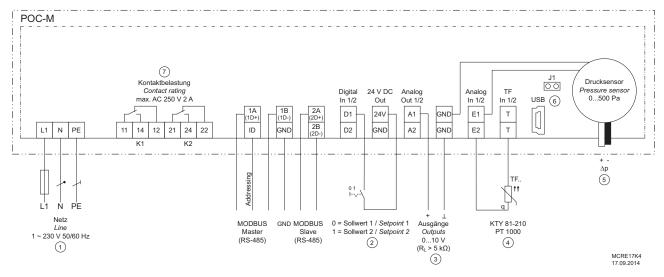
Туре	POC-M		
Part-No.	313833 (320060-42)		
Line voltage	1 ~ 230 V (-15 % bis +10 %), 50/60 Hz		
Weight	0.98 kg		
Input resistance for sensor signal (E2)	for 0 - 10 V input: $R_i > 900 k\Omega$ for input 4 - 20 mA: $R_i = 250 \Omega$ (max. load 500 Ω)		
Voltage supply for external devices	+24 V (-30+20 %), I <sub>max</sub> 62 mA		
Analog output (A1, A2 0 - 10 V)	Load resistance (load) > 5 k $\Omega$ Short-circuit proof, short-circuit current = 24 mA		
Digital inputs (D1, D2)	R <sub>i</sub> approx. 7.8 kΩ Input current typ. 2.5 mA Voltage range high level: 7.119 V DC Voltage range low level: 02.7 V DC		
Max. heat dissipation	approx. 10 W		
Max. line fuse	10 A		
Max. permissible ambient temperature	55 °C		
Min. permissible ambient temperature	0 °C (if mains voltage is not switched off up to -20 °C)		
Permissible rel. humidity	85 % no condensation		
Electromagnetic compatibility for the standard voltage	Interference emission EN 61000-6-3 (domestic household applications)		
230 / 400 V according to DIN IEC 60038	Interference immunity EN 61000-6-2 (industrial applications)		
Housing protection	IP54		

## Connectable conductors (information for all terminals)

Rerminals		Cross section min.	Cross section max.		
	Terminal range, rated connection	0.13 mm <sup>2</sup>	1.5 mm <sup>2</sup>		
	Wire connection cross section AWG	AWG 24	AWG 16		
	Solid H05(07) V-U	0.2 mm <sup>2</sup>	1.5 mm <sup>2</sup>		
	Flexible H05(07) V-K	0.2 mm <sup>2</sup>	1.5 mm <sup>2</sup>		
	With wire end ferrule DIN 46 228/1	0.25 mm <sup>2</sup>	1.5 mm <sup>2</sup>		
	Wire plastic collar ferrule DIN 46 228/4	0.25 mm <sup>2</sup>	0.75 mm <sup>2</sup>		
	Rigid conductors and conductors with wire end ferrules can be plugged into the terminal without tools. Use the flexible conductor for connection and the push button for release. Stripping length: 8 mm				
	r to the connection possibilities of the terminals. The necessary conductor c the respective prevailing conditions.	ross section must b	e dimensioned		



#### 13.2 **Connection diagram**



1 Line

- 2 3 Digital inputs for potential-free contacts, D1 pre-programmed for switch over setpoint 1/2
- Outputs ( $I_{max} = 2$  mA): A1 pre-programmed control output e.g. for controlling a speed controller. Fans with integrated controller and input 0 -10 V can be activated directly. A2 pre-programmed for constant voltage +10 V Outdoor temperature sensor to E2: TF.. (KTY, Pt1000), alternatively 0...10 V, 0...20 mA, 4...20 mA,
- 4

5

Internal pressure sensor to E1 Jumper J1 for USB interface (Bootloader) Contact rating max. AC 250 V 2 A (ohmic load) 6 7

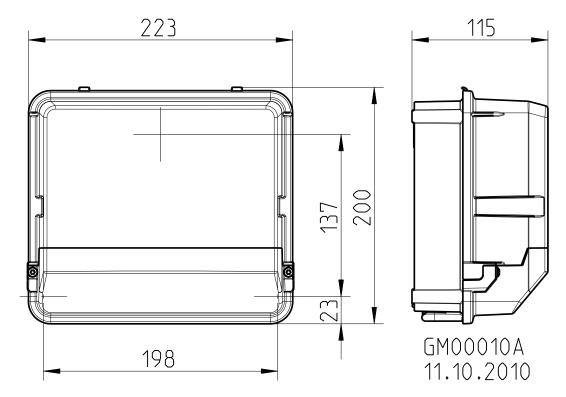
#### Attention!

Plug the jumper J1 to both PINs only for a software update via USB interface. The device will not switch on if this jumper is plugged to both PINs!

Do not replug the jumper under voltage, observe the safety instructions!



## 13.3 Dimensions [mm]





#### 13.4 Index

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# 13.5 Manufacturer reference **( €**

Our products are manufactured in accordance with the relevant international regulations. If you have any questions concerning the use of our products or plan special uses, please contact:

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